

# Laser Marker

# Communication Interface **User's Manual**

for MD-X1000/1500 Series **MD-F3200/5200 Series MD-U1000 Series ML-Z9600 Series** 





Read this manual before using the system in order to achieve maximum performance.

Keep this manual in a safe place for future reference

# **Symbol**

read these messages carefully.		
A DANGER	It indicates a hazardous situation which, if not avoided, will result in death or serious injury.	
	It indicates a hazardous situation which, if not avoided, could result in death or serious injury.	
	It indicates a hazardous situation which, if not avoided, could result in minor or moderate injury.	
NOTICE	It indicates a situation which, if not avoided, could result in product damage as well as property damage.	
► Important	It indicates cautions and limitations that must be followed during operation.	
N Point	It indicates additional information on proper operation.	
Reference V	It indicates tips for better understanding or useful information.	

The following symbols alert you to important messages. Be sure to

It indicates the reference pages and items in this manual.

# MMD35GB

1	Interface
2	Communication Specifications
3	Command Details
4	Applied Functions
5	Communication Errors
Α	Appendix

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# **Communication command list**

#### Basic

Command function	Command	Ref.
Delete a program	DeleteProgram	12
Confirm the READY status	Ready	12

### Commands related to the guide laser operation



Command function	Command	Ref.
Start the marking	StartMarking	13
Guide laser printing	GuideLaser	13
Stop the guide laser	StopMarking	13
Enable/disable the acceptance of start marking	TriggerLock	13
Turn the distance pointer on/off	DistancePointer	13
Read a 2D code	Check2DCode2	13
Check the focus distance	FocusCheck	14

#### **Current values and statuses**



Command function	Command	Ref.
Running program No. (Change/Request)	ProgramNo	14
Current counter value setting (Change/Request)	Counter	14
I/O encoded character (Change/Request)	IoEncodedCharacter	14
Request the final marking string	MarkedCharacter	15
Request the error status	Error	15
Clear an error	ErrorClear	15

### Unit setup/management

inder Setting	Basic Setting	
Disting and of Setting priors  Texal Distance and Pasition Correction  Texal Distance and Pasition  Texal Distance and Pasition	ommunication Setup	Configures settings for all laser markers.
Finder Setting Force Distance and Position Correction	xpansion Processing	Nickname
Fice Distance and Position Correction          Visco Distance and Position Correction         Visco Distance and Position Correction         Visco Distance and Position Correction         Visco Distance and Position Correction         Visco Distance and Position Correction         Visco Distance and Position Correction         Visco Distance and Position Correction         Visco Distance and Position Correction         Mail Position (15P)         The settings         Object of Visco Distance (15P)         Visco Distance (1	/0 Setting	0000000000
Xx       0.000 mm       0.000	inder Setting	
1     0.000 ml xmgt     0.000 ml xmgt     0.000 ml xmgt       2     0.000 ml xmgt     0.000 ml xmgt     0.000 ml xmgt       MIPOSITION (15P)     0.000 ml xmgt     0.000 ml xmgt     0.000 ml xmgt       Tome settems     0.000 ml xmgt     0.000 ml xmgt     0.000 ml xmgt       Toma model and the first to top first a top fir	Option	Focal Distance and Position Correction
Image: Control of the second secon		X: 0.000 mm 0: 0.000 *
AllPosition (15P) Time settings 2015/03/6 ©* 1423:56 © CK Since with PC time TimeSetting(15P) If the should be not and up on the should be all have, power size mode 6 encourse the should be should be all have by pages after the response the should be should be all have by pages after the response the should be should be all have by pages after the response the should be should be all have by pages after the response the should be all have by pages after the should be all have by pages after the response the should be all have by pages after the should be all have		Y: 0.000 ⊕ mm X angle: 0.000 ⊕ ° V 5 θ
Time settings DIS030 * 1+223.50 * * * * * * * * * * * * * * * * * * *		Z: 0.000 🐡 mm Yangle: 0.000 🐡 *
DOLISING TO*         1423-56         OK         Sends with PC text           TimeSetting(15P)         File second of a long of and a long thread the left here are bready by provide and the long with the provide second of a second of the long with the provide second of a second of the long with the provide second of the long with th		AllPosition (15P)
DOLISING TO*         1423-56         OK         Sends with PC text           TimeSetting(15P)         File second of a long of and a long thread the left here are bready by provide and the long with the provide second of a second of the long with the provide second of a second of the long with the provide second of the long with th		Time setting
TimeSetting(15P) If he have been added to the set of th		
If the second of induced the strategy inter though index the strategy prover-sever mode is     encoursely the strategy in the several in prover-sever mode, is strategy strategy as dis free     encourses y the strate state.     the recovery the strate state strategy strategy strategy strategy is     description of provemants and the strategy strategy strategy strategy is     encourses y the strate state.     Set time:         Executions and the strategy		2015/03/06 🐨 14:23:56 🔆 OK Sync with PC time
enabled. When a trigger is received in power-save mode, marking begins after the recovery time elapse. In the orth-filly marking program, despite of parameters, the recovery time is fixed as 0s. Set time:		TimeSetting(15P)
		enabled. When a trigger is received in power-save mode, marking begins after the recovery time elapses. In the on-the-fly marking program, despite of parameters,
Recovery line:		
		Recovery time:

Command function	Command	Ref.
Position correction (Change/Request)	AllPosition	15
Date/time setting (Change/Request)	TimeSetting	15



Command function	Command	Ref.
Laser power offset (Change/Request)	PowerOffset	16
Barcode verification	BarcodeVerification	16

## **Program information**



Command function	Command	Ref.
Workpiece position adjustment (Plane) (Change/Request)	ProgramPosition	18
Correct the height direction (Change/Request)	HeightCorrection	18

Motionless Marking/On-the-fly Ma PositionAdjustment	King The marking score is calculated by analyzing the finder image when the marking is done. The confirmation result is output from I/O.
Marking Confirmation	Marking Confirmation Enable
2D code reader	
Common Setting	Position for Check:
3D Shape List	Block No.: 000 •
	Type: String Horizontal
Option	Contents: ABC ^
	-
	Disabled when a matrix is used.
	Custom Coordinate:
	X: mm
	Y: mm
	Z: mm
	Sensitivity:
	Auto
	💿 Custom 🕂
	Capture delay: 0.0 💿 s
	Error Threshold: Score 50 🗑 NG OK
	CheckMarking (19P)

Command function	Command	Ref.
Marking confirmation function (Change/Request)	CheckMarking	19



Command function	Command	Ref.
2D code reader function (Change/Request)	Check2DCode Quality	19
Reading coordinates of the 2D code reader function (Change/Request)	Check2DCode QualityPosition	19



Common block marking parameters Com		
(Change/Request) Parameters	monMarking meter	20

ogram settings Motionless Marking/On-the-fly Marking PositionAdjustment	Sets program related options.
Marking Confirmation	Update Character Setting
2D code reader	This is enabled when performing matrix marking or continuous marking.
Common Setting 3D Shape List	MarkingEnergy (20P)
Option	Marking Energy Check
	Set upper limit threshold:
	Set lower limit threshold:
	Scanner waiting position when ready
	Start Position X:      Annu Marcelland Marcelland     Custom Coordinate V:      Lin mm
	Custom Coordinate      Y1     To the second se
	ScannerWaiting (20P)
	Contrast: 100 👘 %
	Compatibility
	Encode GS1 DataBar CC-A 'C and 'D'     Set approach scan speed
L. L	
	ApproachScanSpeed (20P)
	OK Cancel

Command function	Command	Ref.
Marking Energy Check (Change/Request)	MarkingEnergy	20
Scanner waiting position when ready (Change/Request)	ScannerWaiting	20
Approach scan speed (Change/Request)	ApproachScanSpeed	20

# String/Logo/Barcode setting



Command fu	Inction	Command	Ref.
Block type (Change/Red	quest)	BlockType	21
Barcode type (Change/I	Request)	CodeType	21
Edit block	Edit block	Edit block	
000 String Horizontal Flow •	001 String arc (dockwise) Flow	OO1 Hatch logo     F	low •
Marking Data	Narking Data	hing meters Marking Data	Marking Parameters
String	CharacterString (21	P) File Name	Ref.
Number of dransters: 3 Fort: Bispanner () TrueType Fort Distanded Bispande O Mulpie O Mulpie O Mulpie O Mulpie O Mulpie	Number of characters: Direction: © Coducter Counterclockies Fout: © System font: © TrueType Font (2	0 Store Block Height: 20.500 mm Dlock Wedte: 20.500 mm Dlock Medicate Casto (H) LogoSize (23) 2P)	
Size           Height:         3.000 ⊕ mm □ Proportional           Orarscher         2.000 ⊕ mm □ Ratio Specification           Layout:         Saace	Multple Webble Size Height: 3.000 mm Proportion	Characte Proportional	
CharacterSize (23P)	Character Layout: 2.000  mm Ratio Spec Space  0.500	CharacterRati	0 (23P)
	Arc Radius: 20.000 🕆 mm	ArcCharacter	(24P)
Width: 7.000 mm Height: 3.000 mm	Width: mm Height:	mm Width: 20.560 mm Height:	20.560 mm
< Back(8) Next(N) >	< Back(B) Nex	t(N) > <a></a> < Back(B)	Next(N) >

Command function	Command	Ref.
String and logo files (Change/Request)	CharacterString	21
Font related (Change/Request)	CharacterFont	22
Character size (Change/Request)	CharacterSize	23
Logo size (Change/Request)	LogoSize	23
String proportional setting (Change/Request)	Character Proportional	23
String ratio setting (Change/Request)	CharacterRatio	23
Arc string character layout setting (Change/Request)	ArcCharacter	24



Command function	Command	Ref.
Barcode/2D code related (Change/Request)	CodeSetting	24
Barcode size (Change/Request)	BarcodeSize	25
GS1DataBar size (Change/Request)	GS1DataBarSize	25
DataMatrix size (Change/Request)	DataMatrixSize	25
QR Code size (Change/Request)	QRCodeSize	25



Command function	Command	Ref.
Block position (Change/Request)	BlockPosition	26
Block layout (Change/Request)	BlockLayout	26
Fixed point emission time (Change/Request)	FixedPoint ProcessingTime	26

#### **Marking parameters**



Command function	Command	Ref.
Marking parameters (Change/Request)	MarkingParameter	27
Barcode/2D code pattern setting (Change/Request)	CodePattern	27
Hatch logo pattern setting (Change/Request)	HatchPattern	28
TrueType font pattern setting (Change/Request)	TTFPattern	28
Barcode/2D code fill marking parameters (Change/Request)	CodeFillParameter	28
Hatch logo fill marking parameters	HatchParameter	29
TrueType font fill marking parameters (Change/Request)	TTFParameter	29
Photo setting (Change/Request)	PhotoSetting	30



Command function	Command	Ref.
Marking flag (Change)	MarkingEnable	30
Individual fill marking parameters (Change/Request)	FillMarking Parameter	30
Jump Speed (Change/Request)	JumpSpeed	30
Nudge marking quality setting (Change/Request)	MarkingQuality	31
Approach (Change/Request)	Approach	31
Space approach (Change/Request)	SpaceApproach	31
Curve correction (Change/Request)	CurveCorrection	31

# Code overprinting parameters



Command function	Command	Ref.
Barcode/2D code overprinting marking parameters (Change/Request)	MultiPassMarking Parameter	32
Barcode/2D code overprinting pattern setting (Change/Request)	MultiPassPattern	32
Barcode/2D code overprinting fill	MultiPassFill	33
parameters (Change/Request)	Parameter	00
Quality level of barcode/2D code	MultiPass	33
overprinting (Change/Request)	QualityLevel	55
Approach of barcode/2D code	MultiPassApproach	33
overprinting (Change/Request)		55
Jump speed of barcode/2D code	MultiPass	33
overprinting (Change/Request)	JumpSpeed	55
Space approach of barcode/2D code	MultiPassSpace	33
overprinting (Change/Request)	Approach	55
Curve correction of barcode/2D code	MultiPass	33
overprinting (Change/Request)	CurveCorrection	55
Wait time for start marking of barcode/2D	MultiPassBlock	34
code overprinting (Change/Request)	MarkingDelayTime	54

## 3D shape setting



command function	Commanu	IVEI.
3D shape setting (Change/Request)	3DShape	34
3D shape type (Change/Request)	3DShapeType	34
3D shape position (Change/Request)	3DShapePosition	35
Diameter of cylinder shape (Change/Request)	CylinderDiameter	35
Cone shape size setting (Change/Request)	ConeSize	35
Diameter of sphere shape (Change/Request)	SphereDiameter	36
Position on 3D shape (Change/Request)	3DSurfacePosition	36
Cone setting (Change/Request)	ConeSetting	36

## Matrix setting



Command function	Command	Ref.
Matrix row & column setting (Change/Request)	MatrixSetting	37
Matrix size setting (Change/Request)	MatrixSize	37
Matrix cell reference point (Change/Request)	CellReferencePoint	37
Cell individual setting (Change/Request)	MatrixCell	37
Cell marking flag (Change)	MatrixCellEnable	38
Matrix position setting (Change/Request)	MatrixPosition	38
Count using invalid marking cells (Change/Request)	InactiveCellCount	38

#### Group/Counter setting

Group setting (Change/Request)

Counter setting (Change/Request)

Com	piete(C)	Input Cancel
Width: 2.000 mm Height: 3.00	Encoding:	CounterSetting (39P)
GroupOffset (39	P)	Tming: [/0 v
Others		Repetition: 1 2 Step: 1 2
Y: 0.000 (* mm 8: 0.000 (* °		Count Trining: Trigger •
Shift X: 0.000 - mm		Final Value: 4294967295 🚔 Base: 10 👘
Y1 0.000 🕆 mm		Value range Start Value: 0 👘 🗐 Initial Value: 0 👘
Rotation reference point: X: 2.000 + mm	Type:	Individual Counter   Counter Number:
X: 0.000 mm Y: 0.000 mm		1 print(s)
Reference coordinates Movement reference point:		Start Value Final Value 0000000000 0000000000000000000000000
Basic Setting	Sample:	,
000 Group	String:	%0AC0C

GroupOffset

CounterSetting

39

39

#### **Operation information**

The followings are operation information that can be requested on MD-U1000 series.

# The followings are operation information that can be requested on ML-Z9600 series.

The undescribed portions of operation information/cumulative marking count are the same command as MD-U1000 series.



Command function	Command	Ref.
Request on controller operating time	OperatingTime	40
Request on laser exited time	LaserOperatingTime	40
Request on scanner operating time	ScannerOperatingTime	40
Request on number of shutter operations	ShutterOperatingCount	40
Request on number of contactor operations	ContactorOperatingCount	40
Request on head temperature	MarkingUnitTemperature	40
Request on controller temperature (°C)	ControllerTemperature	40
Request on the result of laser power calibration	LaserPowerCalibration Result	40
Cumulative marking count 1 and 2 (change/request)	CumulativeMarkingCount	40
Request on replacing expiration of the dry agent for the head	DesiccantExpirationDate	40

# Request on number of operations of<br/>safety shutter BSafety ShutterBOper<br/>atingCount41Request on laser oscillating tube<br/>temperatureMarkingLaserOscilla<br/>torTemperature41

Command

SafetyShutterAOper

atingCount

Ref.

41

### Laser power measurement (MD-U1000 series only)

Command function

Request on number of operations of

safety shutter A



Command function	Command	Ref.
Laser power measurement	LaserPowerCheck	41

# 1. Interface

Read the "Chapter 2 Safety Information" in the user's manual for the applicable model to perform operation in the state that the safety is secured by using security function even when the network failure occurs.
 Confirm the safe operation by considering the communication dates dates to the communication time on the securement of the safe operation.

communication delay due to the communication time or network overload state.

# 1-1 RS-232C Interface

This section explains how to communicate using RS-232C connection.

#### **Connection cables**

The connector type on the laser marker unit side is D-Sub 9-Pin (Male). When connecting with an external device (PLC, etc.), connect as shown below in solid lines using RS-232C straight cable. The following is an example of connection with an external device with D-Sub 9-Pin connector.

Laser marker s	de		Shield		Exte	rnal device side
	1	]	· · - · - ·	1	1	
Send	2		1	÷→	2	Receive
Receive	3	←	i	<u> </u>	3	Send
	4	1	ļ	:	4	
Signal GND	5 (		<u>.</u>		5	Signal GND
	6		:	: \	6	
	7	]		i —	7	
	8	1	:		8	
	9	]	i	1	9	
Connector ho	bod	<u>}</u>	• •	•—	c	onnector hood

- Important
   The connector will be more susceptible to noise if the connector hood is not conducted with the shield.
  - On some external devices, communication cannot be established without short-circuiting No. 4/6 pins and No. 7/8 pins on the external device side. Refer to the manual of the external device.
- Reference Only No. 2, 3 and 5 pins are used on the laser marker side.
  - If the external device also has 9 pins, data is sent from the laser marker to the external device between No.2 pins and data is sent from the external device to the laser marker between No.3 pins.
  - The type of fixing screws used on the connector hood is M2.6.

## **Communication settings**

The RS-232C communication settings must be configured the same on the laser marker and the external device. Using Marking Builder 3 or the console, configure the settings such that all of the following items are the same.

Setting item	
Baud rate	2400/4800/9600/19200/38400 (Default
	value)/57600/115200 bps
Parity check	None (Default value)/Odd/Even
Stop bit	1 (Default value)/2 bit
Check sum	None (Default value)/Yes

Reference . The delimiter automatically detects the delimiter setting of the external device. [EXT] and [CR] are supported.

- The data length is "8 bits fixed", communication mode is "Full duplex", synchronization mode is "Start-stop synchronization", flow control is "None", and inter-frame timeout is "3500ms".
- It is compliant with the EIA (Electronic Industries Association) RS-232C.
- When sending a non-ASCII string, specify the character code from Unicode (UTF-8), Shift-JIS, or Latin-1. The default value is Unicode (UTF-8). If you are using Marking Builder 3, you can change the setting from [Unit Setup] under [Communication Setup] in the [Laser Marker] tab.

Basic Setting	Configures cor	munication settings for the laser marker side.
Expansion Processing		
L/O Setting	Char code	
Finder Setting	Char code:	Unicode (UTIT-8) ·
Pinder Setting	R5-232C	
option		
	Baud Rate:	38400 bps   Data Length: #bit
	Stop Bit:	1 bit • Parity: none
	Checksum:	None 💌
	Delimiter:	Automatic discrimination (CR or ETX)
	Ethernet	
	Cotain an IP address	automatically (BCOTP)
	P address:	0 0 0 0
	Subnet mask:	0 0 0 0
	Default gateway:	0 0 0 0
	NAC address:	A182-C3-D4E5-F6
	Port number:	50002 Advanced
	Industrial Ethernet	NotLised
		1.001.000.0

<ul> <li>RS-232C is the protocol that may occur the destruction of the part of data (data corruption or failure) due to some noise or poor contacting.</li> <li>Be sure to use the parity or checksum to construct the communication environment with advanced reliability.</li> </ul>

.

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# 1-2 Ethernet interface

This section explains how to communicate using TCP/IP (Non-procedure) via Ethernet.

#### **Connection cables**

UTP) cable.			
	Pin number	MDI signal	Signal function
No. 1 to 8 from top	1	TD+	Sent data (+)
	2	TD-	Sent data (-)
	3	RD+	Received data (+)
	4	-	-
	5	-	-
	6	RD-	Received data (-)
RJ-45 Modular connector	7	-	-
	8	-	-

Connect the laser marker with the external device using a LAN (STP or UTP) cable.

Reference . • Both straight and cross cables are supported. Category 5 cable or higher is recommended.

· Optional LAN cross cable (OP-66843) is sold separately.

#### **Communication settings**

When connecting the laser marker with the external device using TCP/IP via Ethernet, set the IP addresses and subnet masks such that they are in the same local area network. The default port number is "50002".

For details on how to configure the settings, refer to  $\square$ \*5-3 Unit Setup: Ethernet settings" in the Marking Builder 3 User's Manual.

 Important
 In the case of Ethernet communication, the delimiter is fixed to [CR] and the check sum is fixed to [None], respectively.

• If you are using Marking Builder 3, you can change the setting from [Unit Setup] under [Communication Setup] in the [Laser Marker] tab.

	- IC		
Basic Setting		munication settings for the laser marker side.	
Communication Setup	Configures co	munication settings for the laser marker side.	
Expansion Processing			
I/O Setting	Char code		
Finder Setting	Char code:	Unicode (UTF-8)	
	RS-232C		
Option			
	Baud Rate:	38400 bps	bit
	Stop Bit:	[1bit • Parity: [n	ione •
	Chedoum:	None •	
	Delmiter:	Automatic discrimination (CR or ETX)	
	Ethernet		
	Culemer		
	Obtain an IP address	automatically (BOOTP)	
	IP address:	0 0 0 0	
	Subnet mask:	0,0,0,0	
	Default gateway:	0 0 0 0	
	MAC address:	A1-82-C3-D4-E5+F6	
	Port number:	50002 Advanced	
	Industrial Ethernet	Not Used 👻	

- Reference For details about communication methods using Profinet and Ethernet/IP, refer to each manual.
- Y Point When the command is received from multiple external equipment via TCP/IP communication, the command is saved to the buffer (queue) by received order, and the next command is processed after sending out the response.

# 2. Communication Specifications

# 2-1 Write/Read command formats

If you wish to send a command from the external device to the laser marker, it should be sent/received in the format described below.

# Write command format

If the command is changing the setting value of the laser marker or executing an operation, add "WX" on the beginning of the command.

Command	WX,Command [CR]
Response	Normal: WX,OK [CR]
	Error: WX,NG,S***,ErrCode [CR]
An OK respo	onse is returned if the change or instruction specified by the
command is	successful and returns an error response if it fails. For

command is successful and returns an error response if it fails. For more information on the error, refer to ""Communication errors" (Page46).

A response is returned in the timing when the specified change or instruction has completed.

- Reference The spelling of "Command" is not case-sensitive. Both cases will be accepted.
  - The maximum command byte length is 4096 bytes. You need to split the command if you wish to send a longer byte length.
  - The command other than strings is sent in ASCII format.

# **Read command format**

If the command is requesting the setting value or the status of the laser marker, add "RX" on the beginning of the command.
Command RX,Command <sub>ICRI</sub>

# Response RX,OK,Response [CR]

The value and status specified by the command are returned in a response. Since request commands can be sent/received at any time, no errors will occur as long as the communication format is correct. The RX command returns a fixed-length response.

- Reference . The information in brackets [] indicates the control code. [CR] is 0Dh in hexadecimal.
  - Use ASCII when sending double-type characters such as Kanji characters or a Unicode string.
  - Insert a ", " (comma) separator after a command, response or check sum.
  - The maximum response byte length is 4096 bytes.

# 2-2 Target specifier

When sending a command to the laser marker, for most commands, you need to determine the change target in advance. A target specifier is inserted before the command in the form of "Target specifier = Target No.". If you wish to specify multiple targets, they need to be arranged side-by-side. The types of target specifiers and target number ranges are as described below.

	ribed below.						
Target Specifier	Target Range No.	Description					
PRG	0000 to 1999	Specifi	es the p	rogram	No.		
BLK	000 to 255	Specifi	es the b	lock No			
OLP	0 to 9	Specifi	es the o	verprint	ing No.		
3DS	000 to 255	Specifi	es the 3	D shap	e No.		
CEL	00001 to 65025	the ma priority	Specifies the number of rows and columns of the matrix. The number will be assigned with priority given to rows, in reference to the top left of the matrix.				
		000001	000002	000003	000004	000005	000006
		000007	000008	000009	000010	000011	000012
		000013	000014	000015	000016	000017	000018
		000019	000020	000021	000022	000023	000024
		000025	000026	000027	000028	000029	000030
		000031	000032	000033	000034	000035	000036
GRP	000 to 255	Specifi	es the g	roup No	).		i
CTR	0 to 9/A to J	Specifies the counter No.					

- Reference ... A "," (comma) separator is inserted between the target specifier and the command.
  - A target specifier may be unnecessary for commands that directly operate the laser marker.
  - You can also specify CEL using row & column headers. It is specified in the form of "Row number-Column number" in the range between "001-001" and "255-255".

For example, to change a string, you need to specify the program No. and block No. in advance. The command will therefore be as an example described below.

Example of command for changing the string of block No.1 and program No. 1 to "ABC"

Command	WX,PRG=0001,BLK=001,CharacterString=ABC [CR]
Response	WX,OK <sub>[CR]</sub>

# 2-3 Communication format

# Header/Delimiter setting

- RS-232C connection
- A response is returned automatically detecting the header/delimiter as [STX] / [ETX] or [None] / [CR].
- Ethernet connection
   Only [None]/[CR] are supported.

#### [STX]/[ETX] command examples

Command	[STX]WX,Command[ETX]
Response	[STX] WX,OK [ETX]

### [None]/[CR] command examples

Command	WX,Command [CR]
Response	WX,OK [CR]

#### Check sum setting

You can add a check sum for checking the data integrity for RS-232C communication only. A check sum is added immediately before the delimiter as a 2-digit hexadecimal string. The 2-digit string is calculated based on the horizontal parity (XOR). The following shows an example of the commands and calculating formulas.

#### A command example with check sum added



Reference, • The check sum is calculated excluding the header, delimiter and check sum sections.

# 2-4 Communication priority

The laser marker has 6 types of communication paths that generally support simultaneous connections. However, when the laser marker shifts to a specific status via a communication path, priority will be given to the specific communication path. This means that only request commands will be accepted for communication paths other than the priority communication path. The following table shows the conditions under which a priority communication path will occur.

Communication path	Priority acquisition period
External communication (RS-232C/Ethernet)	The length of time from when the WX command is sent until a response is returned     The length of time from when the CreateProgram command is sent until a response is returned from the EndProgram command
Marking Builder 3 (USB/Ethernet)	<ul> <li>During [Marking] tab transition</li> <li>During sample marking mode transition</li> <li>During I/O terminal monitor mode transition</li> <li>During transition of settings and backup data</li> <li>During laser maintenance</li> <li>During power monitor adjustment</li> <li>During auto focus adjustment</li> <li>During finder use</li> </ul>
Console (Dedicated cable)	<ul> <li>During test marking mode transition</li> <li>During terminal block simulate mode transition</li> <li>During transition of settings and backup data</li> <li>During laser maintenance</li> </ul>
MB3 ActiveX (USB/Ethernet)	<ul> <li>Blocking communication: The length of time from when the setting change command is sent until a response is returned</li> <li>Non-blocking communication: The length of time from when the setting change command is sent until the next event is completed</li> </ul>
Profinet and EtherNet/IP (Ethernet)	<ul> <li>The length of time from the start of a setting change instruction, etc. until the operation is completed</li> </ul>

#### How to interpret the command details

This section explains how to interpret the command details using the following command as an example.



specific parameter is "0". \* Since the fixed values are ignored on the laser marker side, values other than the fixed values will be accepted as long as they are within the parameter input range.

#### WX command example

This command changes the scanner waiting position when ready (X: 5mm, Y: 10mm, Z: -5mm) of program No.0005. Command WX,PRG=0005,ScannerWaiting=1,0005.000,0010.000,-005.000 [CR] WX,OK<sub>ICR</sub> Response

#### RX command example

This command requests the scanner waiting position when ready (X: 5mm, Y: 10mm, Z: -5mm) from program No. 0005. RX,PRG=0005,ScannerWaiting [CR] Command

RX,OK,1,0005.000,0010.000,-005.000 [CR Response

#### 3-1 **Basic**

#### 1. Delete a program

Com	mand	DeleteProgram		
Description		Deletes the programs in the laser marker.		
Target		No		
wx	Command	WX,DeleteProgram=A,	<b>A</b> , <b>A</b> , <b>A</b> · · · <sub>[CR]</sub>	
VVX	Response	WX,OK [CR]		
RX	Command	No		
КЛ	Response	INU		
Para	meter	A: 0000 to 1999/9999 Deletes all programs if th program No. to delete/99 You can specify multiple program No. for deletion separating them with com		

command as described below.

WX,DeleteProgram=0001,0002,0005,0006 [CR]

- · When you specify multiple programs, an error will occur if any one of the specified program No. does not exist.

# · If a running program is specified, an error occurs.

#### 2. Confirm the READY status

Com	mand	Ready		
Description		Requests whether the laser marker is in ready status.		
Targe	et	No		
wx	Command	No		
VVA	Response	NU		
RX	Command	RX,Ready <sub>[CR]</sub>		
~~	Response	RX,OK, <b>A</b> <sub>[CR]</sub>		
		<b>A:</b> 0/1/2	0: READY ON	
Parameter			1: READY OFF (Error occurring) 2: READY OFF (Marking or	
			expansion in progress)	

Reference . If the value of parameter A is "1", you cannot perform any marking until the error is cleared. Clear the error using the ErrorClear command. However, if the occurring error is a terminal block status error (T\*\*\*), check the ON/OFF status of the terminal block.

# 3-2 Laser marker operation

#### 1. Start the marking

		-	
Com	mand	StartMarking	
Desc	ription	Starts the marking.	
Targ	et	No	
wx	Command	WX,StartMarking [CR]	
VVX	Response	WX,OK <sub>[CR]</sub>	
RX	Command	No	
RA	Response		
Para	meter	No	

Reference · An error response is returned when marking is canceled from the terminal block, etc.

#### 2. Guide laser printing

Com	mand	GuideLaser		
Description		Starts the guide laser marking using the guide laser type specified by parameter A. The guide laser is emitted once for the same length of time as the marking time; and it is emitted continuously for 30 consecutive seconds for all other emissions.		
Targ	et	No		
wx	Command	WX,GuideLaser=A ICR1		
VVA	Response	WX,OK [CR]		
RX	Command	No		
~~	Response			
Parameter		<b>A</b> : 1 to 5	Guide laser type 1: Once 2: Continuous 3: Area frame 4: Workpiece 5: Block frame	

Reference, • This command returns a response as soon as the guide laser emission starts.

The emission can be canceled using the "StopMarking" command.

#### 3. Stop the guide laser

Com	mand	StopMarking	
Desc	ription	Cancels the guide laser marking.	
Targe	et	No	
wx	Command	WX,StopMarking [CR]	
VVA	Response	WX,OK <sub>[CR]</sub>	
RX	Command	No	
RA	Response	NO	
Para	meter	No	

#### 4. Enable/disable the acceptance of start marking

Com	mand	TriggerLock		
Description		Enables/disables acceptance of triggers from the		
Dest	anption	terminal block a	nd/or communication path.	
Targe	et	No		
wx	Command	WX,TriggerLock	(=A <sub>[CR]</sub>	
VVA	Response WX,OK			
RX	Command RX,TriggerLock		[CR]	
КЛ	Response RX,OK,A			
<b>A</b> : 0		<b>A:</b> 0/1	Acceptance of start marking	
Parameter			0: Enabled	
Parameter			1: Disabled	
			* Default value "0"	

Reference · If this command is received during marking, the marking will not stop but the next marking start input will be rejected.

#### 5. Turn the distance pointer on/off

Com	mand	DistancePointer		
Desc	ription	Turns on/off the distance pointer.		
Targe	ət	No		
wx	Command	WX,DistancePoi	nter=A [CR]	
VV X	Response	WX,OK <sub>ICR1</sub>		
RX	Command	RX,DistancePointer		
КЛ	Response	RX,OK, <b>A</b> <sub>[CR]</sub>		
		A: 0/1 Distance Pointer		
Parameter			0: Off	
	1: On		1: On	

Reference . This command returns a response as soon as the distance pointer is turned on/off.

#### 6. Read a 2D code

Command		Check2DCode2	
Deer	vintion	Reads the 2D code inside th	e area using the built-in
Description		camera.	-
Targe	et	No	
wx	Command	WX,Check2DCode2=A,B,C,	<b>D</b> , <b>E</b> , <b>F</b> <sub>[CR]</sub>
	Response	WX,OK, <b>G</b> , <b>H</b> <sub>[CR]</sub>	
RX	Command	No	
100	Response		1
Parameter		<b>A</b> : 0/1/2	Capture position 0: Current scanner position 1: Custom coordinate 2: Block coordinate
		<b>B:</b> Depends on the area size Normal(X): -062.500 to 0062.500 Other model: ""X coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	X coordinate (mm) *A: Fixed value of "0" when 0/2
		C: Depends on the area size Normal(X): -062.500 to 0062.500 Other model: □□"Y coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	Y coordinate (mm) *A: Fixed value of "0" when 0/2
		D: Depends on the area size Normal(X): -021.000 to 0021.000 Other model: □"Z coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	Z coordinate (mm) *A: Fixed value of "0" when 0/2
		<i>E</i> : 0 to 100	Reading area (%) "0" for no specified area ( <b>A</b> : Same as 100% when 0/1, <b>A</b> : Auto area specification when 2)
		<b>F</b> : 0 to 255	Block No. * <b>A:</b> Fixed value of "0" when 0/1
		G: A to D/F	AIM-DPM total grade
		H: Encoded string	Encoded string of 2D code

- - You cannot use on the MD-X1000L/1500L series,
    - MD-F3200/5200 series and ML-Z9600 series.
  - A: When it is 2, what can be read is from after marking to the next marking.

## 7. Check the focus distance

Com	Command FocusCheck		
Description		workpiece and the re of times specified in	nce between the distance to the ference distance for the number parameter A and returns its e focus deviation amount.
Targe	et	No	
wx	Command	WX,FocusCheck=A [CR]	
VVA	Response	WX,OK, <b>B</b> <sub>[CR]</sub>	
RX	Command	No	
Response			
Doro	motor	A: 01 to 10	Measurement count (times)
Parameter		<b>B:</b> -100.0 to 0100.0	Focus deviation amount (mm)

Reference, • If the Z coordinate of the position correction has been input, this value will be subtracted from the focus deviation amount.

· You cannot use on the MD-X1000L/1500L series,

MD-F3200/5200 series and ML-Z9600 series.

# 3-3 Current values and statuses

#### 1. Running program No. (Change/Request)

Command ProgramNo		ProgramNo	
Description		Changes/requests the currently running program	
		No.	
Targe	et	No	
WX Command		WX,ProgramNo=A [CR]	
VVA	Response	WX,OK [CR]	
RX Command		RX,ProgramNo [CR]	
Response		RX,OK, <b>A</b> [CR]	
Parameter		A: 0000 to 1999	Specifies the Program No.

 $\fboxspace{-1mu}{${}_{\mbox{\tiny Reference}_{\mbox{\tiny V}}$}$   $\bullet$  The S021 communication error "Program No. Not

- Registered Error" is returned if you specify a non-registered program No.
  - An OK response is returned when a currently running program No. has been specified. At that point in time, the READY output becomes OFF for an instant due to switching of the program No.

#### 2. Current counter value setting (Change/Request)

Com	mand	Counter	
Description		Specifies the counter No. and changes/requests the current counter value and the current repetitive marking count.	
Targ	et	PRG=0000 to 1999,C1	FR=0 to 9/A to J,
wx	Command	WX,PRG=0000,CTR=0,Counter=A,B [CR]	
VVA	Response	WX,OK <sub>[CR]</sub>	
RX	Command	RX,PRG=0000,CTR=0,Counter [CR]	
КЛ	Response	RX,OK, <b>A</b> , <b>B</b> <sub>ICR1</sub>	
Parameter		<b>A:</b> 000000000 to 4294967295	Current counter value
		<b>B</b> : 00000000 to 4294967295	Repetitive marking count

#### 3. I/O encoded character (Change/Request)

Com	Command IoEncodedCharacter		
Description		Changes/requests the encoded character.	string to use as the I/O
Targe	Target No		
WX Command		WX,IoEncodedCharacter=A [CR]	
VVA	Response	WX,OK [CR]	
Command		RX,IoEncodedCharact	er <sub>ICR1</sub>
RX Response RX,OK,A <sub>[CR]</sub>		RX,OK,A [CR]	
Parameter		<b>A</b> : 00 to 35	Specify the I/O encoded character

Reference - • This command returns a response very quickly as it is processed immediately regardless of the program's expansion time.

#### 4. Request final marking string

Command		MarkedCharacter	
Description		Specifies the program No. and block No. and requests the string marked by the laser marker.	
Targe	et	No	
wx	Command	No	
VVA	Response		
RX	Command	RX,MarkedCharacter= <b>A</b> , <b>B</b> <sub>[CR]</sub>	
RA	Response	RX,OK, C <sub>[CR]</sub>	
		A: 0000 to 1999	Program No.
Para	meter	<b>B</b> : 000 to 255	Block No.
		C: Text	Marking string

Reference . The update characters are returned in the form of an actual marking string.

 Make sure to send this command after the marking. The S029 communication error "Mark data request error" is returned if you send the command without performing any marking.

- In matrix marking, the response returns the mark data of the last marked cell (block).
- If you requested something in relation to the block other than the character strings, "" (blank data) will be returned in the response.

#### 5. Request the error status

Command		Error	
Description		Requests the error o	ccurring in the laser marker.
Target		No	
wx	Command	No	
**^	Response	NO	
RX	Command	RX,Error [CR]	
КЛ	Response	RX,OK, <b>A</b> , <b>B</b> , <b>B</b> , <b>B</b> • • • <sub>[CR]</sub>	
Parameter		<b>A</b> : 0,1	Displays the status of the errors. If no error is occurring, the response returns "0", if it is, "1".
		<b>B</b> : E001 to E400/ W100 to W200/ T000 to T100	Displays the currently occurring errors in comma delimited format.

Reference · If multiple errors are occurring in the laser marker, a response is returned in comma delimited format as follows. RX,OK,1,E001,E002,W100,T000 [CR]

• For details of each error, refer to the User's Manual of the laser marker unit.

#### 6. Clear an error

Com	mand	ErrorClear	
Description		Clears the errors currently occurring in the laser	
Dest	inption	marker.	
Targe	et	No	
wx	Command	WX,ErrorClear [CR]	
VVA	Response	WX,OK [CR]	
RX	Command	No	
RX	Response		
Parameter		No	

Reference . An error cannot be cleared unless its cause has been rectified.

- When you send the ErrorClear command with the cause of the laser marker error unresolved, an "OK" response is returned but the error status will not be cleared.
- Check the ON/OFF state of the terminal block because the error clear cannot be performed for the terminal block error (T\*\*\* error except T000).
- The error clear can be performed for T000 (during remote interlock) if the remote interlock terminal is in a short-circuit.

# 3-4 Unit setup/management

#### 1. Position correction (Change/Request)

Con	Command AllPosition			
Description		Changes/requests the position correction in the Unit Setup.		
Targ	jet	No		
wx	Command	WX,AllPosition=A,B,C,D,E,F [CR]		
VV.	Response	WX,OK [CR]		
RX	Command	RX,AllPosition [CR]		
~~	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> , <b>F</b> <sub>[CR]</sub>		
		A: -090.000 to 0090.000	X rotation angle (°) * Default value "0"	
		<b>B:</b> -090.000 to 0090.000	Y rotation angle (°) * Default value "0"	
		<i>C:</i> -180.000 to 0180.000	θ angle (°) * Default value "0"	
Parameter		D: Depends on the area size Normal(X): -062.500 to 0062.500 Other model: I <sup>III</sup> *X/Y coordinates position correction in the unit setup" of "Appendix-2 Model-Specific Input Value List" (Page49).	X coordinate correction amount (mm) * Default value "0"	
		<i>E:</i> Depends on the area size Normal(X): -062.500 to 0062.500 Other model: I <sup>III</sup> *X/Y coordinates position correction in the unit setup" of "Appendix-2 Model-Specific Input Value List" (Page49).	Y coordinate correction amount (mm) * Default value "0"	
		F: Depends on the area size Normal(X): -021.000 to 0021.000 Other model: III"Z coordinate position correction in the unit setup" of "Appendix-2 Model-Specific Input Value List" (Page49).	Z correction amount (mm) * Default value "0"	

Reference • This command is applied to all programs. If the program pre-expansion function is enabled, it takes time because the response is returned after all program expansion processings are finished.

- The X/Y rotations angle will be disabled in programs containing blocks having other than a 3D shape of "XY plane".
- The following restrictions exist in the case of on-the-fly marking.
- The coordinate correction with the same coordinate on the movement direction (X/Y coordinate) is disabled
- The rotation correction of the coordinate that crosses orthogonally on the movement direction (X/Y rotation angle) is disabled
- $\theta$  angle can be corrected up to ±2.000°

#### 2. Date/time setting (Change/Request)

Con	nmand	TimeSetting	
Description		Changes/requests the date and time of the internal clock.	
Targ	get	No	
wx	Command	WX,TimeSetting=A,B,C	, <b>D</b> , <b>E</b> , <b>F</b> <sub>[CR]</sub>
VVA	Response	WX,OK [CR]	
RX	Command		
КЛ	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> , <b>F</b> <sub>[CR]</sub>	
		A: 2000 to 2099	Year: 4 digits
		<b>B</b> : 01 to 12	Month
Dore	ameter	<b>C</b> : 01 to 31	Day
Para	ameter	<b>D</b> : 00 to 24	Hour
		<b>E</b> : 00 to 60	Minute
		<b>F</b> : 00 to 60	Second

# 3. Laser power offset (Change/Request)

Command		PowerOffset	
Description		Changes/requests the laser power offset in the Unit Setup.	
Targe	et	No	
wx	Command	WX,PowerOffset=A [CR]	
Response		WX,OK [CR]	
RX Command Response		RX,PowerOffset [CR]	
		RX,OK, <b>A</b> <sub>[CR]</sub>	
Parameter		A: -100.0 to 0100.0 Power offset amount (%) * Default value "0"	

> This command is applied to all programs. If the program pre-expansion function is enabled, it takes time because the response is returned after all program expansion processings are finished.

 This command is not applied to the block whose laser power is 0%.

#### 4. Barcode verification

Com	mand	BarcodeVerification	
Description		This command is used in the barcode verification function. When this command is accepted on the barcode verification screen, the collation string will be associated with the program No. When this command is accepted in Run mode, the settings will switch to the program No. matching the collation string.	
Targ	et	No	
wx	Command	WX,BarcodeVerification=A [CR]	
VVX	Response	WX,OK [CR]	
RX Command Response		No	
		INO	
Parameter		A: Text	Barcode verification string (Max. 20 characters)

Reference · You can access Marking Builder 3's barcode verification screen by following the procedure below. [Laser Marker] tab > [Unit Setup] > [Options] > [Register code] under "Barcode verification"

# 3-5 Program setting

#### 1. Movement/stationary marking setting (Change/Request)

Command		OnTheFly		
Description		Toggles the stationary/movement marking setting and changes/requests the movement direction.		
Target		PRG=0000 to 1999		
wx	Command	WX,PRG=0000,OnT	heFly= <b>A</b> , <b>B</b> <sub>[CR]</sub>	
VVA	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,OnTh	neFly <sub>[CR]</sub>	
~~	Response	RX,OK, <b>A</b> , <b>B</b> <sub>[CR]</sub>		
		A: 0/1 Stationary/Movement marking setting 0: Stationary marking 1: Movement marking * Default value "0"		
Parameter		<b>B</b> : 0 to 3	Moving direction Sets the line flow direction. 0: Bottom 1: Right 2: Top 3: Left *A: Fixed value of "0" when 0	

 $\begin{tabular}{c} \hline $Reference_{$P'$}$ & The line flow direction will be determined in reference to the positional relationship with the head orientation. \end{tabular}$ 

#### 2. Head orientation (Change/Request)

Com	mand	HeadDirection	
Desc	cription	Changes/requests the head orientation.	
Targ	et	PRG=0000 to 1999	
	Command	WX,PRG=0000,Hea	dDirection=A [CR]
wx	Response	WX,OK [CR]	
RX	Command	RX,PRG=0000,Head	dDirection <sub>[CR]</sub>
КЛ	Response	RX,OK,A [CR]	
Parameter		<b>A</b> : 0 to 7	Head orientation Sets the orientation of the head with reference to the marking area. 0: Left 1: Left (Mirror invert) 2: Right (Mirror invert) 3: Right 4: Bottom (Mirror invert) 5: Top 6: Bottom 7: Top (Mirror invert) * Default value "0"

#### 3. Marking order (Change/Request)

Command		MarkingOrder	
Description		Changes/requests the marking order.	
Target		PRG=0000 to 1999	
wx	Command	WX,PRG=0000,Mark	kingOrder= <b>A</b> [CR]
VVX	Response	WX,OK [CR]	
RX	Command	RX,PRG=0000,MarkingOrder [CR]	
RX	Response	RX,OK, <b>A</b> <sub>[CR]</sub>	
Parameter		<b>A</b> : 0/1	Marking order 0: Group/block no. order 1: Auto * Default value "0"

 $\fboxspace{-1mu}{${}_{\mbox{\tiny Reference}_{\mbox{\tiny V}}$}$   $\bullet$  This command is only enabled for stationary marking.

#### 4. Continuous stationary marking (Change/Request)

Command Contir		ContinuousStationary	Marking	
Description		Changes/requests the enable/disable, marking count and interval of the continuous marking function in		
		stationary marking.		
Targ	jet	PRG=0000 to 1999		
	Command	WX,PRG=0000,Continue	ousStationaryMarking=A,B,C	
wx	Command	[CR]		
	Response			
RX	Command	RX,PRG=0000,ContinuousStationaryMarking <sub>ICR1</sub>		
RA	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> <sub>[CR]</sub>		
		<b>A:</b> 1/2	Continuous marking setting	
			1: Disabled	
			2: Enabled	
			* Default value "1"	
Para	ameter	<b>B</b> : 00002 to 65535	Continuous marking count	
			(times)	
			*A: Fixed value of "2" when 1	
		C: 0000.0 to 0009.9	Continuous interval (s)	
			*A: Fixed value of "0" when 1	

Reference ... • This command is only enabled for stationary marking.

### 5. Movement parameters (Change/Request)

Command         OnTheFlyMarking           Description         Changes/requests the movement parameters of the movement marking function.           Target         PRG=0000 to 1999           WX         Command         WX,PRG=0000,OnTheFlyMarking=A,B,C,D <sub>ICRI</sub> Rx         Command         RX,PRG=0000,OnTheFlyMarking_ICRI           Rx         Command         RX,PRG=0000,OnTheFlyMarking_ICRI           Rx         Command         RX,PRG=0000,OnTheFlyMarking_ICRI           Response         RX,OK,A,B,C,D_ICRI         Moving method           0: Constant         1: Encoder           * Default value "0"         B: Depends on the area size           Normal(X):         Normal(X):           0000.1 to 4000.0         Other model:           D"-Line speed" of "Appendix-2         Model-Specific Input Value           List" (Page49).         C: 0           C: 0         Fixed value           D: 001.0 to 200.0         Encoder pulse count           (Pulse/mm)         * Default value "Normal: 50"/							
Description         movement marking function.           Target         PRG=0000 to 1999           WX         RG=0000, OnTheFlyMarking=A, B, C, D <sub>[CR]</sub> Rx         Command           Rx         Command           Rx         Command           Rx,PRG=0000,OnTheFlyMarking_ICRI           Rx         Command           Rx,PRG=0000,OnTheFlyMarking_ICRI           Response         RX,OK,A,B,C,D ICRI           Moving method         0: Constant           1: Encoder         * Default value "0"           B: Depends on the area size         Line speed (mm/s)           Normal(X):         *A: Fixed value of "0.1"           0000.1 to 4000.0         *A: Fixed value "Normal:           U"Line speed" of "Appendix-2         Model-Specific Input Value           List" (Page49).         150"           C: 0         Fixed value           D: 001.0 to 200.0         Encoder pulse count           (Pulse/mm)         * Default value "Normal: 50"/	Command		OnTheFlyMarking				
Target     PRG=0000 to 1999       WX     PRG=0000, On TheFlyMarking=A,B,C,D <sub>[CR]</sub> Response     WX,OK <sub>[CR]</sub> Response     RX,PRG=0000,OnTheFlyMarking <sub>ICR]</sub> Response     RX,OK,A,B,C,D <sub>[CR]</sub> A: 0/1     Moving method 0: Constant 1: Encoder * Default value "0"       B: Depends on the area size Normal(X): 0000.1 to 4000.0 Other model: D*Line speed" of "Appendix-2 Model-Specific Input Value List" (Page49).     Line speed mm/s) *A: Fixed value of "0.1" when 1 * Default value "Normal: 300"/"Wide: 450"/"Small: 150"       C: 0     Fixed value       D: 001.0 to 200.0     Encoder pulse count (Pulse/mm) * Default value "Normal: 50"/	Description		Changes/requests the movement parameters of the				
Wx         Command Response         WX,PRG=0000,OnTheFlyMarking=A,B,C,D <sub>[CR]</sub> Rx         Command Response         RX,PRG=0000,OnTheFlyMarking <sub>[CR]</sub> Rx         RX,OK,A,B,C,D <sub>[CR]</sub> Moving method 0: Constant 1: Encoder * Default value "0"           B: Depends on the area size Normal(X): 0000.1 to 4000.0 Other model: U <sup>*1</sup> Line speed" of "Appendix-2 Model-Specific Input Value List" (Page49).         Moving method 0: Constant 1: Encoder * Default value "0"           Command         C: 0         Fixed value           D*Line speed" of "Appendix-2 Model-Specific Input Value List" (Page49).         Fixed value           C: 0         Fixed value         Encoder pulse count (Pulse/mm) * Default value "Normal: 50"/			movement marking function.				
WX         Response         WX,OK <sub>ICR1</sub> Rx         Command Response         RX,PRG=0000,OnTheFlyMarking <sub>ICR1</sub> Rx         Response         RX,OK,A,B,C,D <sub>ICR1</sub> A: 0/1         Moving method 0: Constant 1: Encoder * Default value "0"           B: Depends on the area size Normal(X): 0000.1 to 4000.0 Other model: ID*Line speed" of "Appendix-2 Model-Specific Input Value List" (Page49).         Moving method 0: Constant 1: Encoder * Default value of "0.1" when 1 * Default value "Normal: 150"           C: 0         Fixed value Encoder pulse count (Pulse/mm) * Default value "Normal: 50"/	Targ	get	PRG=0000 to 1999				
Response       WX,OK [CR]         Rx       Command Response       RX,PRG=0000,OnTheFlyMarking [CR]         Response       RX,OK,A,B,C,D [CR]       Moving method 0: Constant 1: Encoder * Default value "0"         B: Depends on the area size Normal(X): 0000.1 to 4000.0 Other model: III*Line speed" of "Appendix-2 Model-Specific Input Value List" (Page49).       Line speed (mm/s) *A: Fixed value of "0.1" when 1 * Default value "Normal: 300"/"Wide: 450"/"Small: 150"         C: 0       Fixed value D: 001.0 to 200.0       Fixed value Encoder pulse count (Pulse/mm) * Default value "Normal: 50"/		Command	WX,PRG=0000,OnTheFlyMa	arking= <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> [CR]			
Response         RX,OK,A,B,C,D <sub>ICRI</sub> A: 0/1         Moving method 0: Constant 1: Encoder * Default value "0"           B: Depends on the area size Normal(X): 0000.1 to 4000.0 Other model: ID*Line speed" of "Appendix-2 Model-Specific Input Value List" (Page49).         Line speed (mm/s) *A: Fixed value of "0.1" when 1 * Default value "Normal: 300"/"Wide: 450"/"Small: 150"           C: 0         Fixed value           D: 001.0 to 200.0         Encoder pulse count (Pulse/mm) * Default value "Normal: 50"/	VVA	Response	WX,OK [CR]				
B: Depends on the area size Normal(X):         Line speed (mm/s) *A: Fixed value "0"           B: Depends on the area size Normal(X):         Line speed (mm/s) *A: Fixed value of "0.1" when 1           Other model:         *Default value "Normal: 000.1 to 4000.0           Other model:         *Default value "Normal: 00"/Wide: 450"/"Small: 150"           Developed of the speed of the sp	DV	Command	RX,PRG=0000,OnTheFlyMa	arking <sub>[CR]</sub>			
Parameter       B: Depends on the area size Normal(X):       Line speed (mm/s) *A: Fixed value of "0.1" when 1         Other model:       "Default value "Normal: 0000.1 to 4000.0       *A: Fixed value of "0.1" when 1         Other model:       "Default value "Normal: 0ther model:       300"/"Wide: 450"/"Small: 150"         III "Line speed" of "Appendix-2 Model-Specific Input Value List" (Page49).       50"         C: 0       Fixed value         D: 001.0 to 200.0       Encoder pulse count (Pulse/mm) * Default value "Normal: 50"/	RA	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> <sub>[CR]</sub>				
Parameter       1: Encoder * Default value "0"         B: Depends on the area size Normal(X): 0000.1 to 4000.0 Other model: IIII-Line speed" of "Appendix-2 Model-Specific Input Value List" (Page49).       Line speed (mm/s) *A: Fixed value of "0.1" when 1 * Default value "Normal: 300"/"Wide: 450"/"Small: 150"         C: 0       Fixed value         D: 001.0 to 200.0       Encoder pulse count (Pulse/mm) * Default value "Normal: 50"/			<b>A:</b> 0/1	Moving method			
B: Depends on the area size Normal(X):         Line speed (mm/s)           000.1 to 4000.0         *A: Fixed value of "0.1"           Other model:         * Default value "Normal: 000.1 to 4000.0           Other model:         300"/"Wide: 450"/"Small: 150"           Model-Specific Input Value List" (Page49).         150"           C: 0         Fixed value           D: 001.0 to 200.0         Encoder pulse count (Pulse/mm)           * Default value "Normal: 50"/				0: Constant			
B: Depends on the area size Normal(X):       Line speed (mm/s)         Normal(X):       *A: Fixed value of "0.1"         0000.1 to 4000.0       when 1         Other model:       * Default value "Normal:         ID*Line speed" of "Appendix-2 Model-Specific Input Value List" (Page49).       300"/Wide: 450"/"Small:         C: 0       Fixed value         D: 001.0 to 200.0       Encoder pulse count (Pulse/mm)         * Default value "Normal: 50"/				1: Encoder			
Parameter         Normal(X): 0000.1 to 4000.0 Other model: Uffulter speed" of "Appendix-2 Model-Specific Input Value List" (Page49).         *A: Fixed value of "0.1" when 1 * Default value "Normal: 300"/Wide: 450"/"Small: 150"           C: 0         Fixed value           D: 001.0 to 200.0         Encoder pulse count (Pulse/mm) * Default value "Normal: 50"/				* Default value "0"			
Parameter       0000.1 to 4000.0 Other model: U"Line speed" of "Appendix-2 Model-Specific Input Value List" (Page49).       when 1 * Default value "Normal: 300"/"Wide: 450"/"Small: 150"         C: 0       Fixed value         D: 001.0 to 200.0       Encoder pulse count (Pulse/mm) * Default value "Normal: 50"/			B: Depends on the area size	Line speed (mm/s)			
Parameter       Other model:       * Default value "Normal:         ''Line speed" of "Appendix-2       300"/"Wide: 450"/"Small:         Model-Specific Input Value       150"         List" (Page49).       Fixed value         D: 001.0 to 200.0       Encoder pulse count (Pulse/mm)         * Default value "Normal: 50"/			Normal(X):	*A: Fixed value of "0.1"			
Parameter         Image: Constraint of the speed of			0000.1 to 4000.0	when 1			
Line speed" of "Appendix-2       300"/"Wide: 450"/"Small:         Model-Specific Input Value       150"         List" (Page49).       150"         C: 0       Fixed value         D: 001.0 to 200.0       Encoder pulse count (Pulse/mm)         * Default value "Normal: 50"/	Dor	omotor	Other model:	* Default value "Normal:			
List" (Page49). C: 0 Fixed value D: 001.0 to 200.0 Encoder pulse count (Pulse/mm) * Default value "Normal: 50"/	Faid	ameter	<sup>1</sup> "Line speed" of "Appendix-2	300"/"Wide: 450"/"Small:			
C: 0 Fixed value D: 001.0 to 200.0 Encoder pulse count (Pulse/mm) * Default value "Normal: 50"/			Model-Specific Input Value	150"			
D: 001.0 to 200.0 Encoder pulse count (Pulse/mm) * Default value "Normal: 50"/			List" (Page49).				
(Pulse/mm) * Default value "Normal: 50"/			<b>C</b> : 0	Fixed value			
* Default value "Normal: 50"/			<b>D</b> : 001.0 to 200.0	Encoder pulse count			
				(Pulse/mm)			
"Wide: 20"/"Small: 100"				* Default value "Normal: 50"/			
				"Wide: 20"/"Small: 100"			

Reference · This command is only enabled for movement marking.

# 6. Movement marking trigger delay (Change/Request)

Com	mand	OnTheFlyTriggerDelay		
Description		Changes/requests the "distance to the sensor" and "marking position offset" of the movement marking function.		
Targe	ət	PRG=0000 to 1999		
wx	Command		heFlyTriggerDelay= <b>A</b> , <b>B</b> [CR]	
***	Response	WX,OK <sub>[CR]</sub>		
RX	Command	RX,PRG=0000,OnTheFlyTriggerDelay		
~~	Response	RX,OK, <b>A</b> , <b>B</b> <sub>[CR]</sub>		
Parameter		<b>A</b> : 0000.0 to 1200.0	Distance to sensor (mm) * Default value "Normal: 62.6(X/F/U), 60.1(Z)"/ "Wide:165.1(X/U), 150.1(F/Z)"/ "Small: 25.1"	
		<b>B:</b> -1200.0 to 01200.0	Marking position offset (mm) * Default value "0"	
Refe	Reference . • This command is only enabled for movement marking.			

 Configure the setting such that the sum of "the distance to the sensor" and "marking position offset" is greater than the start position in the movement range setting. If the movement range setting is disabled, values smaller than the default value will not be accepted.

### 7. Continuous movement marking (Change/Request)

Command		OnTheFlyContinuousMarking		
Description		Changes/requests the enable/disable, marking count and interval of the continuous marking function in movement marking.		
Targe	ət	PRG=0000 to 1999		
wx	Command	WX,PRG= <b>0000</b> , On = <b>A</b> , <b>B</b> , <b>C</b> <sub>[CR]</sub>	TheFlyContinuousMarking	
	Response	WX,OK [CR]		
RX	Command	RX,PRG= <b>0000</b> , On <sup>-</sup>	TheFlyContinuousMarking [CR]	
КЛ	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> <sub>[CR]</sub>		
Parameter		<b>A</b> : 0/1/2	Continuous marking setting 0: Mark while trigger ON 1: Continuous marking disabled 2: Continuous marking enabled * Default value "1"	
		<b>B</b> : 00002 to 65535	Continuous marking count (times) * <b>A:</b> Fixed value of "2" when 0/1	
		<b>C:</b> 0000.1 to 1200.0	Continuous interval (mm) * <b>A:</b> Fixed value of "100" when 1	

 $\square_{\text{Reference}_{p'}}$  • This command is only enabled for movement marking.

## 8. Marking range setting (Change/Request)

Con	nmand	OnTheFlyMarkingArea		
Description		Changes/requests the enable/disable, start position and end position of the marking range setting of the movement marking function.		
Targ	jet	PRG=0000 to 1999		
wx	Command	WX,PRG=0000,OnTheFlyMarkin	IgArea= <b>A</b> , <b>B</b> , <b>C</b> <sub>[CR]</sub>	
**^	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,OnTheFlyMarking	gArea <sub>[CR]</sub>	
~~	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> <sub>[CR]</sub>		
Parameter		A: 0/1 B: Depends on the area size Normal(X):-062.500 to 0062.500 Other model: <sup>CD</sup> "Start Position" of "Appendix-2 Model-Specific Input Value List" (Page49).	Marking range setting 0: Disabled 1: Enabled * Default value "0" Start position (mm) * Default value "Normal: 31.25(X/F/U), 30.00(Z)"/ "Wide:82.5(X/U),75(F/Z)" /"Small: 12.5"	
		C: Depends on the area size Normal(X):-062.500 to 0062.500 Other model: "I"End Position" of "Appendix-2 Model-Specific Input Value List" (Page49).	End position (mm) * Default value "Normal: -31.25(X/F/U), -30.00(Z)"/ "Wide:-82.5(X/U),-75(F/ Z)"/"Small: -12.5"	

 $\fbox{Reference}_{\Gamma} \bullet \text{ This command is only enabled for movement marking.}$ 

#### 9. Workpiece position adjustment (Plane) (Change/Request)

	•	position aujustitient (Flane) (Ch	lange/nequeet/	
Command		ProgramPosition		
Description		Changes/requests the correction inside the horizontal plane in the workpiece position adjustment.		
Targ	get	PRG=0000 to 1999		
wx	Command	WX,PRG=0000,ProgramPosition	= <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> <sub>[CR]</sub>	
VV X	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,ProgramPosition	[CR]	
RA	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> <sub>[CR]</sub>		
		A: Depends on the area size Normal(X):-062.500 to 0062.500 Other model: <sup>CIII</sup> Movement reference point X/Y coordinates" of "Appendix-2 Model-Specific Input Value List" (Page49).	Movement reference point X(mm) * Default value "0"	
		<b>B:</b> Depends on the area size Normal(X):-062.500 to 0062.500 Other model: <sup>CIII</sup> Movement reference point X/Y coordinates" of "Appendix-2 Model-Specific Input Value List" (Page49).	Movement reference point Y(mm) * Default value "0"	
Para	ameter	C: Depends on the area size Normal(X):-125.000 to 0125.000 Other model: Ш"Correction amount X/Y" of "Appendix-2 Model-Specific Input Value List" (Page49).	X coordinate correction amount (mm) * Default value "0"	
		D: Depends on the area size Normal(X):-125.000 to 0125.000 Other model: <sup>CD</sup> <sup>are</sup> Correction amount X/Y" of "Appendix-2 Model-Specific Input Value List" (Page49).	Y coordinate correction amount (mm) * Default value "0"	
		<i>E:</i> -180.000 to 0180.000	θ angle correction amount (°) * Default value "0"	

• Workpiece position adjustment is only enabled for stationary marking.

#### 10. Correct the height direction (Change/Request)

Command HeightCorrection					
		Changes/requests the correction method and setting			
Description		values for the workpiece position correction in the			
		height direction.			
Targ	ot	PRG=0000 to 1999			
Tary	Command		otion-ABCDEE		
WX		WX,PRG=0000,HeightCorrection=A,B,C,D,E,F <sub>[CR]</sub>			
	Response	WX,OK <sub>[CR]</sub>			
RX	Command	RX,PRG=0000,HeightCorrect	Clion [CR]		
	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> , <b>F</b> <sub>[CR]</sub>			
		<b>A:</b> 0/5/6	Height correction method		
			0: Fixed		
			5: External displacement		
			sensor		
			6: Auto focus		
			* Default value "0"		
		B: Depends on the area size	Correction amount Z		
		Image: Contract Co	coordinate (mm)		
		amount" of "Appendix-2	*A: Fixed value of "0" when		
		Model-Specific Input Value	5/6		
		List" (Page49).	* Default value "0"		
		<b>C</b> : 1 to 9	Measurement count (times)		
			*A: Fixed value of "3" when		
			0		
			* Default value "3"		
		D: Depends on the area size	Upper tolerance limit (mm)		
Daw		Normal(X):	*A: Fixed value of "21"		
Para	ameter	-20.999 to 042.000	when 0		
		Other model:	* Default value "21"		
		<sup>III</sup> "Upper tolerance limit" of			
		"Appendix-2 Model-Specific			
		Input Value List" (Page49).			
		E: Depends on the area size	Lower tolerance limit (mm)		
		Normal(X):	*A: Fixed value of "-21"		
		-42.999 to 020.999	when 0		
		<sup>□</sup> "Lower tolerance limit" of	* Default value "-21"		
		"Appendix-2 Model-Specific			
		Input Value List" (Page49).			
		<b>F:</b> 1/2	If out of range,		
			1: Mark (warning output)		
			2: Do not mark (error output)		
			*A: Fixed value of "1" when		
			0		
			-		
			* Default value "1"		

Reference • The auto focus function of parameter A will be disabled for movement marking.

• You cannot use Auto Focus on the MD-X1000L/1500L series, MD-F3200/5200 series and ML-Z9600 series.

#### 11. Marking confirmation function (Change/Request)

<b>C</b> = m	-	ChaokMarking	
Com	mand	CheckMarking Changes/requests the enable	o/disable of the marking
Description			
		confirmation function and the	e various settings.
Target		PRG=0000 to 1999	
	Command	WX,PRG=0000,CheckMarkin	ng
wx		=A,B,C,D,E,F,G,H,I,J <sub>[CR]</sub>	
	Response	WX,OK <sub>[CR]</sub>	
Command BX PRG=0000 CheckMarking row		1 <b>g</b> [CR]	
100	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> , <b>F</b> , <b>G</b> , <b>H</b> , <b>I</b> , <b>J</b>	[CR]
		A: 0/1      B: 0/1      C: 000 to 255      D: Depends on the area size     Normal(X):     -062.500 to 0062.500     Other model:      III"X coordinate" of     "Appendix-2 Model-Specific     Input Value List" (Page49).	Marking confirmation 0: Disabled 1: Enabled * Default value "0" Position to check 0: Block No. specification 1: Custom coordinate specification * Default value "0" Block No. * <b>B</b> : Fixed value of "0" when 1 * Default value "0" Reading X coordinate * <b>B</b> : Fixed value of "0" when 0 * Default value "0"
Para	meter	E: Depends on the area size Normal(X): -062.500 to 0062.500 Other model: □"Y coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	Reading Y coordinate * <b>B</b> : Fixed value of "0" when 0 * Default value "0"
		F: Depends on the area size Normal(X): -021.000 to 0021.000 Other model: Ш"Z coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	Reading Z coordinate *B: Fixed value of "0" when 0 * Default value "0"
		<b>G</b> : 0/1	Sensitivity setting 0: Auto 1: Any value * Default value "0"
		<i>H</i> : 000 to 100	Sensitivity * <i>G:</i> Fixed value of "50" when 0 * Default value "50"
		<i>I</i> : 000 to 100	Error threshold * Default value "50"
		<b>J</b> : 0.0 to 9.9	Capture delay * Default value "0"

 $\fbox{Reference} \cdot This command is only enabled for stationary marking.$ 

• You cannot use on the MD-X1000L/1500L series, MD-F3200/5200 series and ML-Z9600 series.

• Cannot be set when the 2D code reader function is enabled.

 Specify the reading coordinate in the "Custom Coordinate Specification" when the matrix function is used or 3D shaped block is read.

# 12.2D code reader function (Change/Request)

Com	mand	Check2DCodeQual	ity
Description		Changes/requests the enable/disable of the 2D code quality check function when the marking is complete and the various setting values.	
Targ	et	PRG=0000 to 1999	
wx	Command	WX,PRG=0000,Che	ck2DCodeQuality= <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b>
	Response	WX,OK [CR]	
RX	Command	RX,PRG=0000,Chec	k2DCodeQuality <sub>[CR]</sub>
КЛ	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> [CF	र।
		<b>A</b> : 0/1	0: Quality check disabled 1: Quality check enabled * Default value "0"
		<b>B</b> : 000 to 255	Reading target block No. * Only a 2D code block can be specified * <b>A</b> : Fixed value of "0" when 0 * Default value "0"
Para	meter	<b>C:</b> 0.0 to 9.0	Capture delay (s) * <b>A</b> : Fixed value of "0" when 0 * Default value "0"
		<b>D:</b> 0.0 to 9.0	Image hold time (s) * Default value "5"
		<b>E</b> : 0 to 4	Error threshold 0: Total grade A or higher 1: Total grade B or higher 2: Total grade C or higher 3: Total grade D or higher 4: Total grade F or higher * Default value "4"

Reference, • This command is only enabled for stationary marking. • You cannot use on the MD-X1000L/1500L series, MD-F3200/5200 series and ML-Z9600 series.

 Cannot be set when the marking confirmation function is enabled.

# 13. Reading coordinates of the 2D code reader function (Change/Request)

<u> </u>	Snange/Requ					
Com	mand	Check2DCodeQualityPosition				
Description		Changes/requests whether the reading destination of the 2D code quality check function when the marking is complete is a block No. or Custom coordinates.				
Targ	et	PRG=0000 to 1999				
WX Command		WX,PRG=0000,Check2DCoc C,D <sub>[CR]</sub>	leQualityPosition= <b>A</b> , <b>B</b> ,			
	Response	WX,OK [CR]				
RX	Command	RX,PRG=0000,Check2DCod	eQualityPosition [CR]			
INA.	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> <sub>[CR]</sub>				
Parameter		A: 0/1 B: Depends on the area size Normal(X): -062.500 to 0062.500 Other model: U"*X coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	0: Block No. specification 1: Custom coordinate specification * Default value "0" Reading X coordinate *A: Fixed value of "0" when 0 * Default value "0"			
		C: Depends on the area size Normal(X): -062.500 to 0062.500 Other model: D'Y coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49). D: Depends on the area size Normal(X):	Reading Y coordinate *A: Fixed value of "0" when 0 * Default value "0" Reading Z coordinate *A: Fixed value of "0"			
		O21.000 to 0021.000 Other model: <sup>IIII</sup> "Z coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	when 0 * Default value "0"			

Reference · This function is only applied when the 2D code reader function is enabled.

- You cannot use on the MD-X1000L/1500L series,
- MD-F3200/5200 series and ML-Z9600 series.

• Specify the reading coordinate in the "Custom Coordinate Specification" when the matrix function is used.

#### 14. Common block marking parameters (Change/Request)

	Common Marking parameters (C						
Command	CommonMarkingParamete Changes/requests the comm						
Description							
Torget	parameters that can be used commonly in programs. PRG=0000 to 1999						
Target	WX,PRG=0000 to 1999 WX,PRG=0000,CommonMarkingParameter=A,B,C,D,						
wx Command		$IRingParameter - \mathbf{A}, \mathbf{B}, \mathbf{C}, \mathbf{D},$					
	<b>E</b> , <b>F</b> , <b>G</b> , <b>H</b> , <b>I</b> , <b>J</b> , <b>K</b> , <b>L</b> <sub>[CR]</sub>						
Response							
RX Command	, ,						
Response	RX,OK,A,B,C,D,E,F,G,H,I,J,						
	<b>A:</b> 000.0 to 100.0	Common laser power (%)					
		* Default value "0"					
	<b>B</b> : Depends on the area size	Common scan speed					
	Normal(X):00001 to 12000	(mm/s)					
	Other model:	* Default value "1000"					
	<sup>□</sup> "Scan speed" of "Appendix-2						
	Model-Specific Input Value						
	List" (Page49).						
	C: Differs depending on the	Common pulse frequency					
	model	(kHz)					
	Normal(X):000 to 400	* Default value "100"					
	Other model:						
	<sup>(1)</sup> "Pulse frequency" of						
	"Appendix-2 Model-Specific						
	Input Value List" (Page49).	O second statut					
	<b>D</b> : Depends on the area size	Common spot variable * Default value "0"					
	Normal(X):-210 to 0210 Other model:						
	<sup>©</sup> "Spot variable" of						
	"Appendix-2 Model-Specific						
	Input Value List" (Page49).						
	<i>E</i> : 001 to 100	Common marking count					
	2.00110100	(times)					
		* Default value "1"					
	F: Depends on the area size	Common Z coordinate					
	Normal(X):	(mm)					
	-21.000 to 0021.000	* Default value "0"					
Parameter	Other model:						
	<sup>I</sup> <sup></sup>						
	"Appendix-2 Model-Specific						
	Input Value List" (Page49).						
	<b>G:</b> 0.000 to 1.000	Common fill interval (mm)					
		* Default value "0.06"					
	H: 00 to 04/06	Common quality level					
		00: Top speed					
		01: Speed priority					
		02: Standard					
		03: High quality					
		04: Top quality					
		06: Top speed 2					
		* Default value "2"					
	<i>I</i> : 00.000 to 10.000	Common skip cross (mm)					
		* Default value "0"					
	<b>J</b> : 0/1	End Point Control:					
		0: Optimize					
	W 000 1 000	1: Custom					
	<b>K</b> : 000 to 200	End Point ON Control (%)					
		*J: Only enabled when "1"					
		is set					
	L : 000 to 200	Default value: "100"					
	L: 000 to 200	End Point OFF Control (%)					
		*J: Only enabled when "1"					
		*J: Only enabled when "1"					

Reference You cannot use Top Speed 2 on the MD-F3200/5200 series, MD-U1000/1500 series and ML-Z9600 series.

• You cannot use End Point Control on the MD-X1000/1500 series and MD-U1000/1500 series.

#### 15. Marking energy check (Change/Request)

Con	nmand	MarkingEnergy				
Des	cription	Changes/requests the ON/OFF of the marking energy				
20000.000		check function and the t	hreshold setting.			
Target		PRG=0000 to 1999				
wx	Command	WX,PRG=0000,Marking	Energy= <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> <sub>[CR]</sub>			
~~~	Response	WX,OK [CR]				
RX	Command	RX,PRG=0000,Marking	Energy <sub>[CR]</sub>			
RX	Response	RX,OK, <i>A</i> , <i>B</i> , <i>C</i> , <i>D</i> <sub>[CR]</sub>				
		<b>A:</b> 0/1	Lower limit threshold			
			0: Disabled			
			1: Enabled			
			* Default value "0"			
		<b>B:</b> 0/1	Upper limit threshold			
			0: Disabled			
Para	ameter		1: Enabled			
			* Default value "0"			
		C: 00000.01 to 99999.99	Lower limit threshold (J)			
			*A: Fixed value of "0.01" when 0			
		D: 00000.01 to 99999.99	Upper limit threshold (J)			
			*B: Fixed value of "0.01" when 0			
	• Marking energy check will be canceled when the next					

Reference, • Marking energy check will be canceled when the next trigger is accepted within 2 seconds of completion of the marking. Therefore, make sure to allow at least 2 seconds between the marking completion and the next marking start.

You cannot use on the ML-Z9600 series.

#### 16. Scanner waiting position when ready (Change/Request)

Con	nmand	ScannerWaiting	• • •			
Description		Changes/requests the scanner waiting position when				
		ready.				
Targ		PRG=0000 to 1999				
wx	Command	WX,PRG=0000,ScannerWaitin	g= <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> <sub>[CR]</sub>			
	Response	WX,OK [CR]				
RX	Command	RX,PRG=0000,ScannerWaiting				
IXA.	Response	RX,OK, <i>A</i> , <i>B</i> , <i>C</i> , <i>D</i> <sub>[CR]</sub>				
Parameter		<b>A</b> : 0/1	Standby coordinate 0: Drawing Start Position 1: Custom coordinate * Default value "0"			
		B: Depends on the area size Normal(X): -062.500 to 0062.500 Other model: □ <sup>w</sup> X coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	Standby X coordinate (mm) * <b>A:</b> Fixed value of "0" when 0			
		C: Depends on the area size Normal(X): -062.500 to 0062.500 Other model: "U"Y coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	Standby Y coordinate (mm) * <b>A:</b> Fixed value of "0" when 0			
		D: Depends on the area size Normal(X): -021.000 to 0021.000 Other model: □□"Z coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	Standby Z coordinate (mm) * <b>A:</b> Fixed value of "0" when 0			

 $\label{eq:Reference} \fbox{$\mathsf{Reference}_{\mathsf{F}}$} \bullet $ If you set the start position as the standby coordinate, the scanner will wait near the first block to be marked. }$ 

# 17. Approach scan speed (Change/Request)

Cor	mmand	and ApproachScanSpeed			
Des	scription	Changes/requests the approa	ch scan speed.		
Target PRG=0000 to 1999					
wx	Command	WX,PRG=0000,ApproachSca	nSpeed=A [CR]		
VVA	Response	WX,OK [CR]			
RX Command		RX,PRG=0000,ApproachScanSpeed [CR]			
КЛ	Response	RX,OK, <b>A</b> [CR]			
A: Depends on the area size Approach so Normal(X):00000 to 04000 (mm/s)		Approach scan speed (mm/s) * Default value "1000"			

# 3-6 String/Logo/Barcode setting

#### 1. Block type (Change/Request)

Com	mand	BlockType			
Desc	cription	Changes/requests the block type.			
Targ	et	PRG=0000 to 1999, BLK=000 to 255			
wx	Command	WX,PRG=0000,BLK	= <b>000</b> ,BlockType= <b>A</b> [CR]		
VVX	Response	WX,OK [CR]			
RX	Command	RX,PRG=0000,BLK=	=000,BlockType		
κX	Response	RX,OK,A [CR]			
Para	meter	<b>A:</b> -04 to 004/009	Block type -04: Hatch logo -03: Photo -02: Workpiece image logo -01: Logo 000: Horizontal characters 001: Vertical characters 002: Arc clockwise 003: Arc counterclockwise 004: Fixed point 009: Barcode, 2D code		

Reference · When creating a new block, send this command to a non-registered block No.

- When you change the block type, the association with the 3D shape No. and the X/Y/Z coordinate layout information will be initialized.
- Fixed point is only supported in stationary marking.
- When the changing command is sent, the character string becomes (a) space(s).

#### 2. Barcode type (Change/Request)

Com	nmand	CodeType		
Des	cription	Changes/requests the barcode type.		
Targ	et	PRG=0000 to 199	9, BLK=000 to 255	
wx	Command	WX,PRG=0000,Bl	_K= <b>000</b> ,CodeType= <b>A</b> [CR]	
VV X	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,BL	K=000,CodeType [CR]	
RX	Response	RX,OK,A [CR]		
Para	umeter	<b>A</b> : 01 to 18	Barcode type 01: CODE39 02: ITF 03: 2of5 04: NW7 05: JAN 06: CODE128 07: QR Code Model 1 08: QR Code Model 2 09: Micro QR Code 10: DataMatrix ECC200 11: GS1 DataBar(Truncated) 12: GS1 DataBar(Truncated) 12: GS1 DataBar(Truncated) 12: GS1 DataBar Stacked 14: GS1 DataBar Stacked CC-A 13: GS1 DataBar Limited 16: GS1 DataBar Limited 16: GS1 DataBar Limited 16: GS1 DataBar Limited 17: GS1 DataBar Limited 18: CODE93 * Default value "1"	

Reference + This command can be sent to a block No. having the block type (BlockType) of "09: Barcode/2D Code".

#### 3. String and logo files (Change/Request)

Com	mand	CharacterString	g
<b>Description</b> Changes/requests the string or logo/photo file.			sts the string or logo/photo file.
Targ	Target PRG=0000 to 1999, BLK=000 to 255		
WX Command		WX,PRG=0000,	BLK=000,CharacterString=A [CR]
**^	Response	WX,OK [CR]	
PY	Command		BLK=000,CharacterString [CR]
IXA.	Response	RX,OK,A [CR]	
Para	RA		<ul> <li>If the block type is "-4 to -1", the parameters are sent in the following format:</li> <li>Logo: %L<file name=""></file></li> <li>External character %F<file name=""></file></li> <li>Workpiece image: %K<file name=""></file></li> <li>Hatch logo: %T<file name=""></file></li> <li>Grayscale photo(X/U only):</li> <li>%I<file name=""></file></li> <li>High resolution photo (X/U only):</li> <li>%X<file name=""></file></li> <li>If the block type is "0 to 3", send the parameter in string format (in less than 510 single-byte or double-byte characters).</li> <li>If the block type is "9", send a string that adheres to the barcode/2D code character input rules.</li> </ul>

- To send a ", (comma)" as a string, send it in the form of "%044A" (ASCII).
- To send a "%" as a string, send it in the form of "%%" (ASCII).
- To set update characters, send the following in ASCII format.

Turne	Freeding	Without zero suppression		With zero suppression			
Туре	Encoding	Without expiration	With expiration	Without expiration	With expiration		
Year 4	No	%4T∎Y	%4Y	-	-		
Year 2	No	%2T∎Y	%2Y		-		
	Yes	%2P∙T∎Y	%2P•Y				
Year 1	No	%1T∎Y	%1Y	-	-		
	Yes	%1P∙T∎Y	%1P•Y				
Month	No	%02T∎M	%02M	Right-aligned %2T∎M Left-aligned %-2T∎M	Right-aligned %2M Left-aligned %-2M		
	Yes	%2P∙T∎M	%2P•M	-	-		
Day	No	%02T∎D	%02D	Right-aligned %2T∎D Left-aligned %-2T∎D	Right-aligned %2D Left-aligned %-2D		
	Yes	%2P∙T∎D	%2P•D	-	-		
Hour	No	%02T∎h	%02h	Right-aligned %2T∎h Left-aligned %-2T∎h	Right-aligned %2h Left-aligned %-2h		
	Yes	%2P∙T∎h	%2P•h	-	-		
Minute	No	%02T∎m	%02m	Right-aligned %2T∎m Left-aligned %-2T∎m	Right-aligned %2m Left-aligned %-2m		
	Yes	%2P∙T∎m	%2P∙m	-	-		
Second	No		%02s		Right-aligned %2s Left-aligned %-2s		
365 days	No	%03T∎X	%03X	Right-aligned %3T∎X Left-aligned %-3T∎X	Right-aligned %3X Left-aligned %-3X		
	Yes	%3P∙T∎X	%3P•X	-	-		
Day of	No	%1T∎B	%1B	-	-		
week	Yes	%1P∙T∎B	%1P•B		-		
Week	Yes	%2P∙T∎W	%2P•W	-	-		
Time zone	Yes	-	%P•S		-		
I/O encoded	No	-	%1R		-		
character	Yes	-	%1P•R	-	-		

• • is the encoding No. (0 to 9) and ■ is the expiration No. (0 to 9).

#### · To set a counter, send the following in ASCII format.

Turne	Zero suppression	Padding	All	Encoding		
Туре			Alignment	Yes	No	
Serial	No	-	-	%0▲P•C∎C	%0 <b>▲</b> C∎C	
counter	Yes	Auto	-	%P●C∎C	%C∎C	
		Specify	Right-aligned	% <b>▲</b> P•C∎C	%▲C∎C	
		Digits	Left-aligned	%-▲P•C∎C	%- <b>▲</b> C∎C	

• • is the encoding No. (0 to 9), ■ is the counter No. (0 to 9, A to J), and ▲ is the No. of digits (1 to 10).

#### • To set a link, send the following in ASCII format.

Reference	Reference parameters	Setting code
GS1 DataBar	GS1 DataBar	%H<●●1>
GS1 DataBar & CC-A	CC-A	%H<●●2>
Barcode	Add check digit	%H<●●C>
	Add start-stop character	%H<●●●*>
	Add check digit & Add start-stop character	%H<●●C*>
GS1 DataMatrix	Entire encoded string	%H<●●00A>
	Specify AI number (AI added)	%H<●●●▲▲A>
	Specify AI number (AI not added)	%H<●●● ▲ ▲>
Other blocks	-	%H<●●>

• • • • is the block No. (000 to 255) and ▲ ▲ is the referenced Al number (Nth Al).

• The range specification options add the following before the ">" symbol.

"SxxxLxxx": S is set with the start position, L is set with the number of reference characters, and XXX is set with the number of characters (001 to 510).

• Send the following by ASCII when a control code is set to the barcode or 2D code.

Control	Setting	Control	Setting	Control	Setting
code	code	code	code	code	code
NUL	%000A	CR	%013A	SUB	%026A
SOH	%001A	SO	%014A	ESC	%027A
STX	%002A	SI	%015A	FS	%028A
ETX	%003A	DLE	%016A	GS	%029A
EOT	%004A	DC1	%017A	RS	%030A
ENQ	%005A	DC2	%018A	US	%031A
ACK	%006A	DC3	%019A	DEL	%127A
BEL	%007A	DC4	%020A	FNC1	%901A
BS	%008A	NAK	%021A	FNC2	%902A
HT	%009A	SYN	%022A	FNC3	%903A
LF	%010A	ETB	%023A	FNC4	%904A
VT	%011A	CAN	%024A		
FF	%012A	EM	%025A		

#### 4. Font related (Change/Request)

• •		ChausstauFaut		
Command		CharacterFont		
Description		Changes/requests the font No., line type, line width, line count and overlap rate used in a string.		
Targ	et	PRG=0000 to 1999, BLK=	000 to 255	
WX Command		WX,PRG= <b>0000</b> ,BLK= <b>000</b> ,	CharacterFont=A,B,C,D,E,F	
**^	Response	UCR] WX,OK [CR]		
		RX,PRG <b>=0000</b> ,BLK <b>=000</b> ,0	CharacterFont	
RX		RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> , <b>F</b> <sub>[CR]</sub>		
	Response	<b>A:</b> 0 to 11	Font No.	
		A: 0 10 11		
			-1: Quick 00: Standard	
			01: Small	
			02 to 11: User font	
			* Quick: Available on only	
			MD-U1000 series	
			* Default value "0"	
		<b>B</b> : 0 to 2	Line type	
			0: Single	
			1: Multiple	
			2: Wobble	
			* Default value "0"	
		C: Depends on the area	Thickness (mm)	
		size	*B: Fixed value of "0.1" when 0	
Dawa		Normal(X):0.010 to 5.000	* Default value "Normal:	
Para	meter	Other model:	0.2"/"Wide: 0.3"/"Small: 0.1"	
		<sup> </sup>		
		"Appendix-2 Model-Specific		
		Input Value List" (Page49).		
		<b>D</b> : 0/1	Auto number of lines	
			0: Any value	
			1: Auto	
			*B: Fixed value of "0" when 0	
			* Default value "0"	
		<b>E</b> : <b>00</b> 2 to 100	Number of multiples (lines)	
			*D: Fixed value of "2" when 1	
			* Default value "4"	
		<b>F:</b> 75.0 to 98.0	Overlap rate (%)	
			*B: Fixed value of "80" when	
			other than 2	
			* Default value "80"	

Reference - • • This command can be sent to a block No. having the block type (BlockType) of "00: Horizontal characters/01: Vertical characters/02: Arc clockwise/03: Arc counterclockwise". Cannot be sent to the block of TrueTypeFont.

> Multiple and Wobble thicknesses can be set to a ratio of up to x0.2 compared to the smaller character height or width.

#### 5. Character size (Change/Request)

Con	nmand	CharacterSize		
Description		Changes/requests the height, width, character layout, space, full width/full height of a string.		
Targ	get	PRG=0000 to 1999, BLK=000 to		
wx	Command	WX,PRG=0000,BLK=000,Chara	cterSize= <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> , <b>F</b>	
	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,BLK=000,Charac	terSize [CR]	
RA	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> , <b>F</b> <sub>[CR]</sub>		
		A: Depends on the area size Normal(X):000.100 to 125.000 Other model: <sup>CP</sup> Height/width" of "Appendix-2 Model-Specific Input Value List" (Page49).	Height (mm) * Default value "3"	
		B: Depends on the area size Normal(X):000.100 to 125.000 Other model: ""Height/width" of "Appendix-2 Model-Specific Input Value List" (Page49).		
		<b>C</b> : 0/2/3	Character Layout 0: Character space 1: Distribute 3: Character pitch	
Para	ameter	D: Depends on the area size Normal(X):000.000 to 180.000 Other model: □ <sup>ar</sup> Space" of "Appendix-2 Model-Specific Input Value List" (Page49).	Space (mm) * Default value "0.5"	
		E: Depends on the area size Normal(X):000.100 to 180.000 Other model: <sup>CII</sup> "Character full width/full height" of "Appendix-2 Model-Specific Input Value List" (Page49).	Full width/Full height (mm) * Default value "7"	
		F: Depends on the area size Normal(X):-180.000 to 0180.000 Other model: "D"Character pitch" of "Appendix-2 Model-Specific Input Value List" (Page49).	Character pitch * Default value "2"	

Reference, 

 This command can be sent to a block No. having the block type (BlockType) of "00: Horizontal characters/01: Vertical characters/02: Arc clockwise/03: Arc counterclockwise".
 You can only set the character height/width ratio between x0.2 and x5.

- The character width and character spacing cannot be set when the ratio specification or proportional is enabled and when it is TrueTypeFont. Also, they cannot be set when the character spacing of **C** is other than 0.
- C to F: Cannot be set when the character string is circle layout.
- The character pitch can be set for a TrueType font only.

#### 6. Logo size (Change/Request)

Command		LogoSize		
Description		Changes/requests the height and width of a logo		
_		(including hatch logo and work		
Targ		PRG=0000 to 1999, BLK=000		
wx	Command	, ,	oSize= <b>A</b> , <b>B</b> <sub>[CR]</sub>	
***	Response	WX,OK <sub>[CR]</sub>		
RX	Command	RX,PRG=0000,BLK=000,Logo	Size [CR]	
RA	Response			
Dom		A: Depends on the area size Normal(X):000.002 to 125.000 Other model: III"Logo height/width" of "Appendix-2 Model-Specific Input Value List" (Page49).	Logo height (mm) * Default value depends on the original DXF size	
Parameter		<i>B</i> : Depends on the area size Normal(X):000.002 to 125.000 Other model: □□"Logo height/width" of "Appendix-2 Model-Specific Input Value List" (Page49).	Logo width (mm) * Default value depends on the original DXF size	

Reference + This command can be sent to a block No. having the block type (BlockType) of "-4: Hatch logo/-2: Workpiece image/-1: Logo".

• When the aspect ratio is maintained, the logo height is set automatically based on the value of the logo width.

#### 7. String proportional setting (Change/Request)

Con	nmand	CharacterProportional		
		Changes/requests the enable/disable of the		
Des	cription	proportional function and	the minimum character width	
		of a string.		
Targ	get	PRG=0000 to 1999, BLM	<=000 to 255	
	Command	WX,PRG=0000,BLK=00	0,CharacterProportional=A,B	
WX	Commanu	[CR]		
	Response	WX,OK <sub>[CR]</sub>		
RX	Command	RX,PRG=0000,BLK=000,CharacterProportional [CR]		
КЛ	Response	RX,OK, <b>A</b> , <b>B</b> <sub>[CR]</sub>		
		<b>A:</b> 0/1	Proportional setting	
			0: Disabled	
			1: Enabled	
Para	ameter		* Default value "0"	
		<b>B</b> : 000 to 100	Minimum character width (%)	
			*A: Fixed value of "20" when 0	
			* Default value "20"	
Reference · This command can be sent to a block No. having the block				

[Reference] • This command can be sent to a block No. naving the block type (BlockType) of "00: Horizontal characters/02: Arc clockwise/03: Arc counterclockwise".

#### 8. String ratio setting (Change/Request)

Com	nmand	CharacterRatio		
Description		Changes/requests the enable/disable of string ratio		
		setting and the width and spa		
Targ	jet	PRG=0000 to 1999, BLK=00		
wx	Command	WX,PRG=0000,BLK=000,Ch	naracterRatio=A, B, C [CR]	
***	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,BLK=000,Ch	aracterRatio [CR]	
КЛ	Response	RX,OK, <i>A</i> , <i>B</i> , <i>C</i> <sub>[CR]</sub>		
		<b>A</b> : 0/1	Ratio setting	
			0: Disabled	
			1: Enabled	
			* Default value "0"	
		<b>B:</b> 020.00 to 500.00	Character width ratio (%)	
			*A: Fixed value of "20"	
			when 0	
			* Default value "66.67" if	
			the character type is system	
Para	ameter		font and "100" if it is a	
			TrueType font	
		C: Depends on the block type	Character space ratio (%)	
		Horizontal characters/Vertical	*A: Fixed value of "0" when	
		characters: -100.00 to	0	
		1000.00	* Default value "25" when	
		Arc (counter) clockwise string:	the system font, circle	
		0000.00 to 1000.00	layout, and character layout	
			are "character spacing,"	
			and "0" for others.	
_		is command can be cont to a		

Reference, • This command can be sent to a block No. having the block type (BlockType) of "00: Horizontal characters/01: Vertical characters/02: Arc clockwise/03: Arc counterclockwise".

 The ratio specification cannot be set in the case of TrueTypeFont.

#### 9. Arc string character layout setting (Change/Request)

Con	nmand	ArcCharacter		
Description		Changes/request the character layout, radius, space, character angle space and open angle of an arc string.		
Targ	let	PRG=0000 to 1999, BLK=00		
	Command	WX,PRG=0000,BLK=000,Arc	Character=A,B,C,D,E <sub>ICR1</sub>	
wx	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,BLK=000,Arc	Character [CR]	
RX	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> [CR]		
		<b>A</b> : 0 to 2	Arc character layout 0: Character space 1: Angular interval 2: Distribute angle * Default value "0"	
		<b>B</b> : 0000.001 to 9999.99	Arc radius (mm) * Default value "20"	
Parameter		C: Depends on the area size Normal(X):000.000 to 180.000 Other model: III-Arc character space" of "Appendix-2 Model-Specific Input Value List" (Page49).	Arc character space (mm) *A: Fixed value of "0" when other than 0 * Default value "0.5"	
		<b>D</b> : 000.000 to 359.999	Arc character angle space (°) * <b>A:</b> Fixed value of "0" when other than 1 * Default value "10"	
		<i>E</i> : 000.000 to 359.999	Arc open angle (°) * <b>A</b> : Fixed value of "0" when other than 2 * Default value "120"	

Reference, • This command can be sent to a block No. having the block type (BlockType) of "02: Arc clockwise/03: Arc counterclockwise".

#### 10. Barcode/2D code related (Change/Request)

Com	Command CodeSetting			
Description		Changes/requests the format, check digit setting,		
		DataMatrix 06 macro setting, and QR Code error		
			e of a barcode/2D code.	
Targe	et	PRG=0000 to	1999, BLK=000 to 255	
wx	Command	WX,PRG=000	0,BLK=000,CodeSetting=A,B,C,D <sub>[CR]</sub>	
VVA	Response	WX,OK [CR]		
RX	Command	RX,PRG=000	0,BLK=000,CodeSetting [CR]	
~~	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b>		
		<b>A:</b> 0/1/2	Format	
			0: Normal	
			1: Black/White inversion	
			2: Overprinting	
			* Default value "0"	
		<b>B:</b> 0/1	Check Digit	
			0: No	
			1: Yes	
			* Fixed value of "0" when the code type is	
			other than CODE39/ITF/NW7	
			* Default value "0"	
		<b>C:</b> 0/1	C: 0/1 DataMatrix 06 macro 0: No	
Para	meter		1: Add	
			* Fixed value of "0" when the code type is other than DataMatrix ECC200	
			* Default value "0"	
		<b>D</b> : 0/1/2/3	QR Code error correction rate	
		<b>D</b> : 0/1/2/3	0: L (7%)	
			1: M(15%)	
			2: Q(25%)	
			3: H (30%)	
			* Fixed value of "0" when the code type is	
			other than QR Model 1/2 or Micro QR	
			* Default value "3" when the code type	
			is QR model 1/2, "2" when micro QR, and	
			"0" for others.	

Reference + This command can be sent to a block No. having the block type (BlockType) of "09: Barcode/2D Code".

- If "Overprinting" is selected as the format, overprinting No.0 will be assigned to "Base" and overprinting No.1 will be assigned to "Code", respectively. Then, set the overprinting marking parameters (MultiPassMarkingParameter), overprinting pattern (MultiPassPattern), and overprinting fill parameters (MultiPassFillParameters).
- If you set the format to "Normal or Black/White Inversion", the parameters in all overprinting No. will be initialized.
- The format of "2: Overprinting" cannot be selected in the case of JAN/EAN/UPC/GS1 DataBar.
- The error correction proportion of a QR code cannot be set to H (30%) in the case of the micro QR.

#### 11. Barcode size (Change/Request)

Con	nmand	BarcodeSize		
Description		Changes/requests the height, narrow bar, bar ratio and		
		quiet zone width of a barcode		
Targ	get	PRG=0000 to 1999, BLK=000		
wx	Command	WX,PRG=0000,BLK=000,Bar	codeSize=A,B,C,D <sub>[CR]</sub>	
**^	Response	WX,OK <sub>[CR]</sub>		
RX	Command	RX,PRG=0000,BLK=000,Bar	codeSize [CR]	
КЛ	Response			
Bar	ameter	A: Depends on the area size Normal(X):000.200 to 125.000 Other model: <sup>[1]</sup> "Barcode height" of "Appendix-2 Model-Specific Input Value List" (Page49).	Barcode height (mm) * Default value "5"	
Fai	ameter	<b>B:</b> 00.010 to 10.000	Narrow bar (mm) * Default value "0.2"	
		<b>C:</b> 002.0 to 004.0	Bar ratio (x) * Default value "2.5"	
		<b>D</b> : 01 to 99	Quiet zone (x) * Default value "10"	

Reference, 

• This command can be sent to a block No. having the block type (BlockType) of "09: Barcode/2D Code" AND barcode type (CodeType) of "01: CODE39/02: ITF/03: 2of5/04: NW7/05: JAN/06: CODE128/18: CODE93".

- · The bar ratio cannot be set in the case of
- JAN/EAN/UPC/CODE93/CODE128.
- · The quiet zone cannot be set when the format is "Normal."

#### 12. GS1 DataBar size (Change/Request)

-				
Command GS1DataBarSize				
Description		Changes/requests the module width, linear code height, separator height, 2D module height, guard width and quiet zone width of GS1 DataBar.		
Targ	get	PRG=0000 to 1999, BLK=000	) to 255	
WX Command		WX,PRG= <b>0000</b> ,BLK= <b>000</b> ,GS , <b>F</b> <sub>[CR]</sub>		
	Response	WX,OK <sub>[CR]</sub>		
RX	Command	, , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , , ,	IDataBarSize <sub>ICRI</sub>	
~~	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> , <b>F</b> <sub>[CR]</sub>		
		<b>A:</b> 00.010 to 10.000	Module width (mm) * Default value 0.25	
Para	ameter	B: Depends on the area size Normal(X):000.200 to 125.000 Other model: IIII-Linear code height" of "Appendix-2 Model-Specific Input Value List" (Page49). C: 0.010 to 5.000	Linear code height (mm) * Default value "8.25" for GS1 DataBar Truncated, "3" for GS1 DataBar Stacked and "2.5" for GS1 DataBar Limited Separator height (mm) * Fixed value of "0.25" when the barcode type is GS1 DataBar (Truncated) and GS1 DataBar Limited. * Default value "0.25"	
		<i>D</i> : 0.010 to 5.000 <i>E</i> : 00 to 10	2D module height (mm) * Fixed value of "0.5" when the barcode type is other than CC-A * Default value "0.5" Guard (x)	
		<b>F</b> : 01 to 50	* Default value "0" Quiet zone (x) * Default value "1"	

Reference, 
• This command can be sent to a block No. having the block type (BlockType) of "09: Barcode/2D Code" AND barcode type (CodeType) of "11 to 16: GS1 DataBar".

- The guard can be set when the format is "Black/white inversion."
- The quiet zone can be set when CC-A and the format is "Black/white inversion."

# 13. DataMatrix size (Change/Request)

Command		DataMatrixSize	
Description		Changes/requests the symbol size, cell size and quiet	
Dest	npuon	zone width of	DataMatrix.
Target		PRG=0000 to	1999, BLK=000 to 255
wx	Command	WX,PRG=000	0, BLK=000, DataMatrixSize=A, B, C [CR]
VVX	Response	WX,OK <sub>[CR]</sub>	
RX	Command	RX,PRG=000	0,BLK=000,DataMatrixSize [CR]
RX	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b>	[CR]
		A: 0001 to	Symbol size
		0030	0001: 10x10/0002: 12x12/
			0003: 14x14/0004: 16x16/0005: 18x18/
			0006: 20x20/0007: 22x22/0008: 24x24/
			0009: 26x26/0010: 32x32/0011: 36x36/
			0012: 40x40/0013: 44x44/0014: 48x48/
			0015: 8x18/0016: 8x32/0017: 12x16/
Dere	meter		0018: 12x36/0019: 16x36/0020: 16x48/
Para	meter		0021: 52x52/0022: 64x64/0023: 72x72/
			0024: 80x80/0025: 88x88/0026: 96x96/
			0027: 104x104/0028: 120x120/
			0029: 132x132/0030: 144x144
		<b>B:</b> 00.010	Cell size (mm)
		to 05.000	* Default value "0.2"
		<b>C</b> : 01~05	Quiet zone (x)
			* Default value "1"

Reference, • This command can be sent to a block No. having the block type (BlockType) of "09: Barcode/2D Code" AND barcode

type (Block lype) of "09: Barcode/2D Code" AND barcode type (CodeType) of "10: DataMatrix, 17: GS1 DataMatrix".

• The quiet zone cannot be set when the format is "Normal."

#### 14. QR Code size (Change/Request)

Com	mand	QRCodeSize		
		4	version, cell size, and quiet	
Description		zone width of QR Cod		
Targ	et	PRG=0000 to 1999, B		
Command W/X PRG=0000 BLK=000 ORCodeSize=A B				
wx	Response	WX,OK <sub>[CR]</sub>		
Command BX PRG=0000 BLK=000 ORCodeSize com		00 ORCodeSize ropt		
RX	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> <sub>[CR]</sub>		
		<b>A</b> : 0001 to 0005	Version	
			1:1/M1 2:2/M2 3:3/M3	
			4:4/M4 5:5/M5 6 : -/M6	
			7:-/M7 8:-/M8 9:-/M9	
			10 : -/M10 11 : -/M11 12 : -/M12	
			13 : -/M13 14 : -/M14 15 : -/M15	
			16 : -/M16 17 : -/M17 18 : -/M18	
			19 : -/M19 20 : -/M20 21 : -/M21	
			22 : -/M22 23 : -/M32 24 : -/M24	
			25 : -/M25 26 : -/M26 27 : -/M27	
			28 : -/M28 29 : -/M29 30 : -/M30	
			* Default value "0"	
Dara	meter		* The input range for Model 1 is	
Fala	meter		"0 to 14"	
			* The input range for Micro QR	
		<b>B</b> 00 0404 05 000	is "0 to 4"	
		<b>B:</b> 00.010 to 05.000	Cell size (mm)	
		<b>C:</b> 0/1	* Default value "0.2"	
		<b>C:</b> 0/1	Mode Auto 0: Disabled	
			1: Enabled	
			* Default value "1"	
		<b>D</b> : 01 to 05	Quiet zone (x)	
		<b>D</b> . 01 10 05	* Default value "4" for QR	
			Code Model 1/2, "2" for Micro	
			QR Code	
		1	GIT COUC	

Reference, 
• This command can be sent to a block No. having the block type (BlockType) of "09: Barcode/2D Code" AND barcode type (CodeType) of "07: QR Model 1/08: QR Model 2/09: Micro QR".

The mode AUTO cannot be set in the case of the micro QR.
The quiet zone can be set when the format is "Black/white inversion."

## 15. Block position (Change/Request)

Command		BlockPosition		
		Changes/requests the X/Y/Z coordinates and Z		
Description		coordinate reference of the common parameters of a		
		block.		
Targ		PRG=0000 to 1999, BLK=000		
wx	Command	WX,PRG=0000,BLK=000,Bloc	kPosition= <b>A</b> , <b>B</b> , <b>C</b> <sub>[CR]</sub>	
	Response	WX,OK <sub>[CR]</sub>	<b>D</b>	
RX Command			Position [CR]	
	RX Response RX,OK,A,B,C <sub>[CR]</sub>			
		<b>A:</b> Depends on the area size Normal(X):-062.500 to 0062.500	X coordinate (mm) * Default value "0"	
		Other model:	Delault value 0	
		Ψ"X coordinate" of "Appendix-2		
		Model-Specific Input Value List"		
		(Page49).		
		B: Depends on the area size	Y coordinate (mm)	
		Normal(X):-062.500 to 0062.500	* Default value "0"	
		Other model:		
		<sup>III</sup> "Y coordinate" of "Appendix-2		
		Model-Specific Input Value List"		
		(Page49).	Z accordinate (mm)	
		C: Depends on the area size and 3D shape type	Z coordinate (mm) * Fixed value of	
		- The 3D shape is XY plane	"9999.999" if the common	
	Normal(X/F/U/Z)/Wide(X/F/U/Z -021.000~0021.000		block marking parameters	
			are referenced	
		Small: -015.000~015.000(X),	* Default value "0"	
		-002.000~002.000(Z)		
		- The 3D shape is slope		
Para	ameter	Normal: -083.500~0083.500		
		(X/F/U), -081.000~0081.000(Z)		
		Wide: -186.000~0186.000(X/F/U), -171.000~0171.000(Z)		
	-171.000~0171.000(Z) Small: -040.000~0040.000(X),			
		-027.000~0027.000(Z)		
		- The 3D shape is cylinder, cone		
	or sphere			
		Normal(X/F/U/Z):		
	-0261.000~0261.000			
		Wide(X/F/U/Z):		
		-621.000~0621.000		
		Small: -115.000~0115.000(X), -102.000~0102.000(Z)		
		- The 3D shape is Z-map		
		Normal:		
		-125.000~0125.000(X/F/U),		
		-120.000~0120.000(Z)		
		Wide: -330.000~0330.000(X/U),		
		-300.000~0300.000(F/Z)		
		Small(X/Z): -050.000~0050.000		
		, ,		

### 16. Block layout (Change/Request)

Com	mand	BlockLayout		
Deed	rintion	Changes/requests the reference point, block angle,		
Dest	cription	start angle and character angle of a block.		
Targ	et	PRG=0000 to 1999,	BLK=000 to 255	
wx	Command	WX,PRG=0000,BLK	X=000, BlockLayout=A, B, C, D, E [CR]	
Response		WX,OK [CR]		
RX Command RX,PRG=0000,BLK=000,BlockLayour		= <b>000</b> ,BlockLayout <sub>[CR]</sub>		
~~	Response	RX,OK,A,B,C,D,E [C	R]	
		A: 0 to 8	Block reference point:	
			0: Left	
			1: Right	
			2: Center	
			3: Lower left	
			4: Lower right	
			5: Upper left	
			6: Upper right	
			7: Тор	
			8: Bottom	
			* Default value "3"	
		<b>B:</b> -180.000 to	Block angle (°)	
Para	meter	0180.000	* Fixed value of "0" when the block	
			type is arc character	
		<b>0</b> 100 000 l	* Default value "0"	
		<b>C:</b> -180.000 to	Start angle (°)	
		0180.000	* Fixed value of "0" when the block	
			type is other than arc character	
			* Default value "90" for clockwise	
		<b>D</b> : 0/1	"-90" for counterclockwise	
		<b>D</b> : 0/1	Set using character angle 0: Disabled	
			1: Enabled	
			* Default value "0"	
		<i>E</i> : -180,000 to	Character angle (°)	
		0180.000	* Default value "0."	
			belauit value 0.	

 $\fboxspace{-1mu}{Reference} p$   $\bullet$  This command can be sent to a block No. having the block type (BlockType) of other than "04: Fixed point".

#### 17. Fixed point emission time (Change/Request)

Command FixedPointProcessingTime		singTime		
Description		Changes/requests the fixed point emission time.		
Target PRG=0000 to 1999, BLK=000 to 255		9, BLK=000 to 255		
	Command	WX,PRG=0000,BL	K=000, FixedPointProcessingTime	
WX	Commanu	=A <sub>[CR]</sub>		
	Response	WX,OK [CR]		
Command		RX,PRG=0000,BLK=000,FixedPointProcessingTime		
RX	Command	[CR]		
	Response	RX,OK,A <sub>[CR]</sub>		
Dara	motor	A: 00000.1 to	Emission time (ms)	
Parameter		65000.0	* Default value "1"	

 $\fboxspace{-1mu}{\space{-1mu}{$\operatorname{Reference}_{$\operatorname{P}$}$}}$   $\bullet$  This command can be sent to a block No. having the block type (BlockType) of "04: Fixed point".

#### 3-7 Marking parameters

	. Marking parameters (Change/Request)			
Con	nmand	MarkingParameter		
Description		Changes/requests the laser power, scan speed, pulse		
			d marking count of a block.	
Targ	jet	PRG=0000 to 1999, BLK=0		
	Command		MarkingParameter= <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> ,	
wx		<b>E</b> <sub>[CR]</sub>		
	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,BLK=000,N	/larkingParameter [CR]	
100	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> [CR]		
		<b>A:</b> 000.0~100.0	Laser power (%)	
		/ 999.9	* Fixed value of	
			"999.9" if the common block	
			marking parameter is	
			referenced	
			* Default value "0"	
		B: Depends on the area	Scan speed (mm/s)	
		size	* Fixed value of	
		Normal(X):00001 to 12000	"99999" if the common block	
		Other model:	marking parameter is	
		<sup>©</sup> "Scan speed" of	referenced	
		"Appendix-2 Model-Specific	* Default value "1000"	
		Input Value List" (Page49).		
		C: Differs depending on	Pulse frequency (kHz)	
		the model	* Fixed value of	
		Normal(X):000 to 400	"999" if the common block	
Para	ameter	Other model:	marking parameter is	
		<sup><sup>1</sup> "Pulse frequency" of</sup>	referenced	
		"Appendix-2 Model-Specific	* Default value "100"	
		Input Value List (Page49).		
		D: Depends on the area	Spot variable	
		size	* Fixed value of	
		Normal(X):-210 to 0210	"9999" if the common block	
		Other model:	marking parameter is	
		<sup> </sup>	referenced	
		"Appendix-2 Model-Specific	* Default value "0"	
		Input Value List" (Page49).		
		<i>E</i> : 001 to 100	Marking count (times)	
		/ 999	* Fixed value of	
			"999" if the common block	
			marking parameter is	
			referenced	
			* Default value "1"	

# 1. Marking parameters (Change/Request)

# 2. Barcode/2D code pattern setting (Change/Request)

Command		CodePattern		
		Changes/requests the various pattern settings, cell		
Desc	ription	marking order ar	nd cell marking count of a barcode/2D	
		code.	-	
Targe	ət	PRG=0000 to 19	999, BLK=000 to 255	
<b>0</b>		WX,PRG=0000,	BLK=000,CodePattern=A,B,C,D,E,F	
wx	Command	[CR]		
	Response	WX,OK [CR]		
DY	Command	RX,PRG=0000,E	BLK=000,CodePattern [CR]	
RX	Response	RX,OK,A,B,C,D	, <b>E</b> , <b>F</b> <sub>[CR]</sub>	
		A: 000 to Pattern		
		011/254	(QR Code/DataMatrix/Bar Code)	
			000: -/-/Alternate	
			001: Pattern 1/A/Unidirectional	
			002: Pattern 2/B/-	
			003: Pattern 3/C/-	
			004: Pattern 4/D/-	
			005: Pattern 5/E/-	
			006: Pattern 6/F/-	
			007: Pattern 7/Entire pattern 1/- 008: Entire pattern 1/Entire pattern 2/-	
			009: Entire pattern 2/Entire pattern 3/-	
			010: Entire pattern 3/Entire pattern 4/-	
			011: Entire pattern 4/Entire pattern 5/-	
			012: Entire pattern 5/Entire pattern 6/-	
			013: Entire pattern 6/-/-	
			254: Individual/Individual/ -	
			* Default value "9" for QR, DataMatrix,	
			"0" for Bar Code	
			* Entire pattern 5/6: Available on only	
		MD-U1000 series		
		<b>B</b> : 000 to	Finder	
		002/255	000: No	
			001: F1	
			002: F2	
			255: =Cell * Fixed value of "0" when other than QR	
			Code AND B is 0 to 2	
			* Default value "1"	
Para	meter	<b>C</b> : 000 to	Alignment	
		002/255	000: No	
			001: A1	
			002: A2	
			255: =Cell	
			* Fixed value of "0" when other than	
			DataMatrix AND C is 0 to 2	
			* Default value "1"	
		<b>D</b> : 000 to 008	Cell	
			(QR Code/DataMatrix) 000: None/None	
			001: M1/C1	
			002: M2/C2	
			003: M3/C3	
			004: M4/C4	
			005: M5/C5	
			006: M6/C6	
			007: M7/C7	
			008: M8/C8	
			* Default value "1"	
		<i>E</i> : 000 to 003	Cell marking order	
			0: None	
			1: Continuous	
			2: Skip 1 cell 3: Skip 2 cells	
			*A: Fixed value of "0" when 8 to 11	
		<b>F</b> : 001 to 100	Cell marking count (times)	
			* <b>A</b> : Fixed value of "1" when 8 to 11	
			* Default value "1"	
		·		

Reference + This command can be sent to a block No. having the block type (BlockType) of "09: Barcode/2D Code".

• "D: 0" cannot be set when "B: 0/255."

• "D: 0" cannot be set when "C: 0/255."

3

**Command Details** 

## 3. Hatch logo pattern setting (Change/Request)

Command		HatchPattern		
		Changes/requests the fill type, pattern, fill direction,		
Description		start position, fill a	ingle, and fill cross angle of a hatch	
		logo.		
Targ	et		9, BLK=000 to 255	
	Command		LK=000, HatchPattern=A, B, C, D, E, F,	
G ICRI				
	Response	WX,OK [CR]	WX,OK [CR]	
RX	Command	RX,PRG=0000,BLK=000,HatchPattern [CR]		
	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b>		
		A: 0 to 2	Fill Type	
			0: Boundary + Fill	
			1: Fill	
			2: Boundary * Default value "0"	
		<b>B</b> : 0 to 2	Pattern	
		<b>B.</b> 0 10 2	0: Slant	
			1: Cross	
			2: Contour	
			*A: Fixed value of "0" when 2	
			* Default value "0"	
		C: 0 to 5	Slant/Cross direction	
			0: Right to left	
			1: Left to right	
			2: Left to right, Right to left	
			3: Right to left, Left to right	
			4: Left to right, Right to left (High	
			Speed)	
			5: Right to left, Left to right (High Speed)	
			* Fixed value of "2" when A is 0 or B is	
			2	
			* Default value "2"	
Para	meter		*4/5: Available on only MD-U1000	
			series	
		D: 0 to 3	Contour direction	
			0: Clockwise	
			1: Counterclockwise	
			2: Clockwise to Counterclockwise	
			3: Counterclockwise to Clockwise	
			* Fixed value of "0" when A is 2 or B is	
			0/1 * Default velue "0"	
		<b>E</b> : 0/1	* Default value "0" Contour drawing start position	
		<b>E.</b> 0/1	0: Inside	
			1: Outside	
			* Fixed value of "1" when A is 2 or B is	
			0/1	
			* Default value "0"	
		F: 000 to 359	Slant/Cross fill angle (°)	
			* Fixed value of "0" when A is 2 or B is	
			2	
		<b>a</b> ana (	* Default value "0"	
		<b>G:</b> 000 to 359	Cross angle (°)	
			* Fixed value of "0" when A is 2 or B is	
			0/2 * Default velue "0"	
			* Default value "0"	

Reference • This command can be sent to a block No. having the block type (BlockType) of "-4: Hatch logo".

## 4. TrueType font pattern setting (Change/Request)

0.000	Command TTFPattern			
Comn	nand	TTFPattern		
Description		Changes/requests the fill type, pattern, fill direction, fill angle, and fill cross angle of a TrueType font.		
Target		PRG=0000 to 1999, BLK=000 to 255		
wx	Command	WX,PRG=0000,B	LK= <b>000</b> ,TTFPattern= <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> <sub>[CR]</sub>	
~~~	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,BL	_K= <b>000</b> ,TTFPattern <sub>[CR]</sub>	
~~	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b>	0K, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> <sub>[CR]</sub>	
Parameter		<b>A</b> : 0 to 2	Fill Type 0: Boundary + Fill 1: Fill 2: Boundary * Default value "0"	
		B: 0/1 Pattern 0: Slant 1: Cross *A: Fixed value of "0" when 2 * Default value "0"		
		<b>C</b> : 0 to 3	Fill direction 0: Right to left 1: Left to right 2: Left to right, Right to left 3: Right to left, Left to right 4: Left to right, Right to left (High Speed) 5: Right to left, Left to right (High Speed)	
			*A: Fixed value of "2" when 2/3 * Default value "2" *4/5: Available on only MD-U1000 series	
		<b>D</b> : 000 to 359	Fill angle (°) * Fixed value of "0" when 2 * Default value "0"	
		<b>E</b> : 000 to 359	Fill cross angle (°) * Fixed value of "0" when A is 2 or B is 0 * Default value "90"	
<b>Profession</b> • This command can be sent to a block No, having the block				

Reference, • This command can be sent to a block No. having the block type (BlockType) of "00: Horizontal characters/01: Vertical characters/02: Arc clockwise/03: Arc counterclockwise" AND the font type of TrueType font.

# 5. Barcode/2D code fill marking parameters (Change/Request)

Command		CodeFillParameter		
Description		Changes/requests the fill interval and shrink fill of a barcode/2D code.		
Targ	et	PRG=0000 to 1999,	BLK=000 to 255	
wx	Command	WX,PRG=0000,BLK	K=000,CodeFillParameter=A,B <sub>[CR]</sub>	
VVA	Response	WX,OK ICRI		
RX	Command	RX,PRG=0000,BLK	=000,CodeFillParameter [CR]	
КЛ	Response	RX,OK, <b>A</b> , <b>B</b> <sub>[CR]</sub>		
Parameter		<b>A:</b> 0.000 to 1.000/ 9.999	Fill interval (mm) * Fixed value of "9.999" if the common block marking parameter is referenced * Default value "Normal: 0.06"/"Wide: 0.08"/"Small: 0.03"	
		<b>B</b> : -Bar Code: -5.000 to 05.000, QR Code/DataMatrix: -2.500~02.500	Shrink fill (mm) * Default value "0"	

Reference · This command can be sent to a block No. having the block type (BlockType) of "09: Barcode/2D Code".

## 6. Hatch logo fill marking parameters

Command		HatchParameter		
Description		Changes/requests the fill interval, common line interval setting reference, shrink fill, no. of skipped fill lines, overprinting enable/disable, overprinting direction, overprinting count, shrink boundary, boundary fill setting, and printing order of a hatch logo.		
Targ	et	PRG=0000 to 1999	9, BLK=000 to 255	
WX Command Response		WX,PRG=0000,BLK=000,HatchParameter=A,B,C,D, E,F,G,H <sub>ICRI</sub> WX,OK <sub>ICRI</sub>		
	Command		<=000,HatchParameter <sub>ICR1</sub>	
RX	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> ,		
Response		<b>A</b> : 0.000 to 1.000 / 9.999 <b>B</b> : 00.000 to 10.000 <b>C</b> : 000 to 255 <b>D</b> : 0/1	Fill interval (mm) * Fixed value of "9.999" if the common block marking parameter is referenced * Default value "Normal: 0.06"/"Wide: 0.08"/"Small: 0.03" Shrink fill (mm) * Default value "0" Skip line count (lines) * Default value "0" Overprinting setting 0: Disabled 1: Enabled * Default value "0"	
Parameter		<i>E</i> : 0/1 <i>F</i> : 001 to 255 <i>G</i> : 00.000 to 10.000	Overprinting direction 0: Alternate 1: Forward * Default value "0" Overprinting count * Default value "1" Shrink boundary (mm)	
		<i>H:</i> 0/1	* Default value "0" Writing Order 0: Boundary -> Fill 1: Fill -> Boundary * Default value "1"	

Reference + This command can be sent to a block No. having the block type (BlockType) of "-4: Hatch logo" and the fill type in hatch logo pattern setting (HatchPattern) of 0: Boundary + Fill/1: Fill".

## 7. TrueType font fill marking parameters (Change/Request)

Command		TTFParameter		
		Changes/requests the fill interval, common line		
		interval setting reference, shrink fill, no. of skipped fill		
Desc	cription		enable/disable, overprinting	
			ng count, shrink boundary, and	
		writing order of a T		
Targ	et	PRG=0000 to 1999		
	Command		K= <b>000</b> ,TTFParameter= <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> ,	
wx	_	F,G,H <sub>[CR]</sub>		
	Response	WX,OK [CR]		
RX	Command	, ,	K= <b>000</b> ,TTFParameter <sub>[CR]</sub>	
	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> ,		
		A: 0.000 to 1.000	Fill interval (mm)	
		/9.999	* Fixed value of	
			"9.999" if the common block marking	
			parameter is referenced	
			* Default value "Normal:	
			0.06"/"Wide: 0.08"/"Small: 0.03"	
		<b>B</b> : 00.000 to 10.000	Shrink fill	
		<b>0</b> :000 to 055	* Default value "0"	
		<b>C</b> : 000 to 255	Skip line count (lines) * Default value "0"	
		<b>D</b> : 0/1		
		<b>D</b> : 0/1	Overprinting setting 0: Disabled	
			1: Enabled	
Para	meter		* Default value "0"	
		<b>E</b> : 0/1	Overprinting direction	
		<b>L</b> . 0/1	0: Alternate	
			1: Forward	
			* Default value "0"	
		F: 001 to 255	Overprinting count	
			* Default value "1"	
		G: 00.000 to 10.000	Shrink boundary (mm)	
			* Default value "0"	
		<b>H</b> : 0/1	Writing order	
			0: Boundary -> Fill	
			1: Fill -> Boundary	
			* Default value "1"	

# 8. Photo setting (Change/Request)

Com	mand	PhotoSetting		
Description		Changes/requests the gamma correction, contrast, contrast enhancement, brightness, skip dots and intensity of a photo.		
Targe	ət	PRG=0000 to 199	99, BLK=000 to 255	
wx	Command	WX,PRG <b>=0000</b> ,B <b>F</b> <sub>[CR]</sub>	LK= <b>000</b> ,PhotoSetting= <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> ,	
	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,B	LK=000,PhotoSetting [CR]	
КЛ	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b>	<b>E</b> , <b>F</b> <sub>[CR]</sub>	
Parameter		A: 0.01 to 9.99 (High resolution only) B: -128 to 0127 (High resolution only)	Gamma correction * Default value "0.6" Contrast * Default value "0"	
		<b>C:</b> 0/1 (High resolution only)	Contrast enhancement 0: Disabled 1: Enabled * Default value "0"	
		<b>D:</b> -128 to 0127 (High resolution only)	Brightness * Default value "0"	
		E: 1 to 8 (Grayscale only)	Skip dots * Default value "1"	
		F: 1 to 8 (Grayscale only)	Intensity Default value "3"	

Reference, • This command can be sent to a block No. having the block type (BlockType) of "-3: Photo".

You cannot use on the MD-F3200/5200 series.

#### 9. Marking flag (Change)

Command		MarkingEnable	
Desc	cription	Changes the marking flag of a block.	
Targ	et	PRG=0000 to 19	99, BLK=000 to 255
Command		WX,PRG=0000,E	BLK=000,MarkingEnable=A,BBB
WX	Commanu	[CR]	
	Response	WX,OK [CR]	
RX	Command	No	
КЛ	Response	NO	
_		<b>A</b> : 0/1/2	Reset the marking flag 0: Set the marking flag of all blocks to OFF 1: Set the marking flag of all blocks to ON 2: Do not change other than the specified block
Parameter		<b>B</b> : 0/1	Marking flag 0: Do not Mark 1: Mark * You can change the marking flag of continuous blocks in a batch by sending this parameter in multiple digits.

Reference ' • To change the marking flag of multiple blocks in a batch, send parameter B in multiple digits.

To set block No.10 to ON, No.11 to OFF, No.12 to ON and all other blocks to OFF, send the command as described below.

 $WX, PRG \texttt{=} 0000, BLK \texttt{=} 010, Marking \texttt{Enable} \texttt{=} 0, 101_{[CR]}$ 

#### 10. Individual fill marking parameters (Change/Request)

Com	Command FillMarkingParameter				
Con	imano		blo/disable and the patting		
Des	cription	Changes/requests the enable/disable and the setting			
Tana		values of the individual fill parameters of a hatch logo. PRG=0000 to 1999, BLK=000 to 255			
Target					
	Command		FillMarkingParameter=A,B,C		
wx	_	,D,E,F <sub>[CR]</sub>			
Response		WX,OK [CR]			
RX	Command	RX,PRG=0000,BLK=000,F			
Response		RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> , <b>F</b> <sub>[CR]</sub>	Leaff field of City and a second second		
		<b>A:</b> 0/1	Individual fill parameters		
			0: Enabled		
		<b>B</b> 000 0 1 400 0/0 000	1: Disabled		
		<b>B:</b> 000.0 to 100.0/9.999	Fill line laser power (%)		
			* Fixed value of "999.9" if the common block		
			marking parameter is referenced		
			*A: Fixed value of "0" when 1		
			* Default value "0"		
		C: Depends on the area	Fill line scan speed (mm/s)		
		size	* Fixed value of		
		Normal(X):00001 to 12000	"99999" if the common block		
		Other model:	marking parameter is		
		<sup><sup>□</sup> "Scan speed" of</sup>	referenced		
		"Appendix-2 Model-Specific	*A: Fixed value of "1000"		
		Input Value List" (Page49).	when 1		
			* Default value "1000"		
		D: Differs depending on the	Fill line pulse frequency (kHz)		
Dar	ameter	model	* Fixed value of		
Fait	anneter	Normal(X):000 to 400	"999" if the common block		
		Other model:	marking parameter is		
		<sup>1</sup> "Pulse frequency" of	referenced		
		"Appendix-2 Model-Specific	*A: Fixed value of "100" when		
		Input Value List" (Page49).	1 * Defeuthustus #400#		
			* Default value "100"		
		E: Depends on the area size	Fill spot variable * Fixed value of		
		Normal(X):-210 to 0210	"9999" if the common block		
		Other model:	marking parameter is		
		Φ"Spot variable" of	referenced		
		"Appendix-2 Model-Specific	* A: Fixed value of "0" when 1		
		Input Value List" (Page49).	* Default value "0"		
		<b>F</b> : 001 to 100/999	Fill line marking count (times)		
			* Fixed value of		
			"999" if the common block		
			marking parameter is		
			referenced		
			* A: Fixed value of "1" when 1		
			* Default value "1"		

Reference + This command can be sent to a block No. having the block type (BlockType) of "-4: Hatch logo" or TrueTypeFont.

#### 11. Jump Speed (Change/Request)

Command		JumpSpeed	
Description		Changes/requests the jump speed.	
Target			99,BLK=000 to 255
Command		WX,PRG=0000,E	3LK=000,JumpSpeed=A [CR]
wx	Response	WX,OK [CR]	
RX	Command	RX,PRG=0000,BLK=000,JumpSpeed [CR]	
RX	Response RX,OK,A [CR]		
		<b>A:</b> 0/1/2	Jump Speed
			0: Top Speed
Para	ameter		1: High Speed
			2: Medium Speed
			* Default value "0"

Reference • This command is enabled when the quality level (MarkingQuality) is not "05: Customize".

#### 12. Nudge marking quality setting (Change/Request)

	MarkingQuality	
	Changes/requests the skip cross, common skip	
		rence, quality level, common
Description	quality level setting reference, and marking start	
١	wait time of a bloo	ck.
Target	PRG=0000 to 199	99, BLK=000 to 255
WX Command	WX,PRG= <b>0000</b> ,B	BLK=000, MarkingQuality=A, B, C [CR]
Response	WX,OK [CR]	
RX Command	RX,PRG= <b>0000</b> ,B	LK= <b>000</b> ,MarkingQuality <sub>[CR]</sub>
Response	RX,OK, <i>A</i> , <i>B</i> , <i>C</i> <sub>[CR]</sub>	
4	A: 00.000 to	Skip cross (mm)
•	10.000	* Fixed value of
/	/ 99.999	"99.999" if the common block
		marking parameter is referenced
		* Default value "0"
	<b>B</b> : 00 to 06	Quality Level
/	/ 99	00: Top speed
		01: Speed priority
		02: Standard
Parameter		03: High quality
		04: Top quality
		05: Customize
		06: Top speed 2
		* Fixed value of
		"99" if the common block marking
		parameter is referenced
		* Default value "02"
	<b>C:</b> 00000.0 to	Wait time for start marking (ms)
6	65000.0	* Default value "0"

Reference,
 The top Speed 2 is used on MD-X1000/1500 series only.
 The skip cross can be set only for the character strings except TrueTypeFont.

### 13. Approach (Change/Request)

Con	nmand	Approach		
Description		Changes/requests the block approach.		
Target		PRG=0000 to 1999,BLK=000 to 255		
WX Command		WX,PRG=0000,E	BLK= <b>000</b> ,Approach=A [CR]	
***	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,BLK=000,Approach [CR]		
RA	Response	RX,OK, <b>A</b> [CR]		
Parameter		A:Normal,Wide: 0.000 to 5.000, Small: 0.000 to 2.500	Approach (mm) * Default value "0.500"	

#### 14. Space approach (Change/Request)

Command		SpaceApproach		
Description		Changes/requests the space approach.		
Target		PRG=0000 to 1999,BLK=000 to 255		
wx Command WX,PRG=0000,BLK=000,SpaceApproac		WX,PRG=0000,BLK=000,SpaceApproach=A [CR]		
***	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,BLK=000,SpaceApproach [CR]		
Response		RX,OK, <b>A</b> [CR]		
Dore	motor	A:0.000 to 5.000 Space approach (mm)		
Parameter		* Default value "0.250"		

#### 15. Curve correction (Change/Request)

Command		CurveCorrectio	n
Description		Changes/reques	ts the curve correction.
Target		PRG=0000 to 19	99,BLK=000 to 255
WX Command		WX,PRG=0000,E	BLK=000,CurveCorrection=A [CR]
***	Response	WX,OK [CR]	
RX	Command	RX,PRG=0000,BLK=000,CurveCorrection [CR]	
КЛ	Response	RX,OK,A [CR]	
		<b>A:</b> 0/1	Curve correction
Dor	ameter		0: Disabled
Faid	ameter		1: Enabled
			* Default value "1"

Reference > • You cannot use Curve Correction on the MD-F3200/5200 series.

# 3-8 Code overprinting parameters

#### 1. Barcode/2D code overprinting marking parameters (Change/Request) MultiPassMarkingParameter Command Specifies the overprinting order in the barcode/2D code overprinting setting and changes/requests the marking Description parameters. PRG=0000 to 1999,BLK=000 to 255,OLP=0 to 9 Target WX,PRG=0000,BLK=000,OLP=0,MultiPassMarkingPara Command meter=A,B,C,D,E,F,G [CR] WX Response WX,OK [CR] RX,PRG=0000,BLK=000,OLP=0,MultiPassMarkingPara Command meter ICR RX Response RX,OK,A,B,C,D,E,F,G [CR] A: 0 to 2 Format 0: Code 1: Code (Black/white inversion) 2: Base \* Default value "2" B: 000.0 to 100.0/999.9 Laser power (%) \* Fixed value of "999.9" if the common block marking parameter is referenced Default value "0" C: Depends on the area size Scan speed (mm/s) Normal(X):00001 to 12000 Fixed value of Other model: <sup>[1]</sup> "Scan speed" of "99999" if the common "Appendix-2 Model-Specific Input block marking parameter Value List" (Page49). is referenced Default value "1000" D: Differs depending on the Pulse frequency (kHz) model \* Fixed value of Normal(X):000 to 400 "999" if the common Parameter Other model: <sup>11</sup> Pulse frequency block marking parameter of "Appendix-2 Model-Specific is referenced Input Value List" (Page49). \* Default value "100" E: Depends on the area size Spot variable Normal(X):-210 to 0210 \* Fixed value of Other model: "9999.9" if the common 0 "Spot variable" of "Appendix-2 block marking parameter Model-Specific Input Value List" is referenced (Page49). \* Default value "0" F: 001 to 100/999 Marking count (times) \* Fixed value of "999" if the common block marking parameter is referenced \* Default value "1 G: Depends on the area size Deep dig amount (mm) Normal(X):00.000 to 42.000 \* Default value "0" Other model: <sup><sup>1</sup> "Deep dig amount" of</sup> "Appendix-2 Model-Specific Input Value List" (Page49)

Reference · This command can be sent when the type of block

(BlockType) is "09: Barcode/2D code" and the format setting of the barcode or 2D code related settings (CodeSetting) is the block No. of "2: Overprinting."

 The overprinting can be added when insetting No. is specified so that it becomes consecutive number at OLP.

# 2. Barcode/2D code overprinting pattern setting (Change/Request)

(Change/Request)				
	mand	MultiPassPat	tern	
			overprinting order in the barcode/2D	
		code overprinting settings and changes/requests the		
Desc	ription	various pattern settings, cell marking order and cell		
		marking count		
Targ	et	PRG=0000 to 1999,BLK=000 to 255,OLP=0 to 9		
	Command	,	00,BLK=000,OLP=0,MultiPassPattern=	
wx			CRI	
	Response	WX,OK [CR]	0,BLK=000,OLP=0,MultiPassPattern	
RX	Command			
Ĩ	Response	RX,OK,A,B,C		
A: 000 to Pattern				
		011/254	(QR Code/DataMatrix/2D Code base/Bar	
			Code/Bar Code base)	
			000: -/-/-/Alternate/- 001: Pattern	
			1/A/B1/Unidirectional/Alternate	
			002: Pattern 2/B/B2/-/Unidirectional 003:	
			Pattern 3/C/B3/-/Alternate (Horiz.)	
			004: Pattern 4/D/B4/-/Unidirectional	
			(Horiz.)	
			005: Pattern 5/E/B5/-/-	
			006: Pattern 6/F/B6/-/- 007: Pattern 7/Entire pattern 1/B7/-/-	
			008: Entire pattern 1/Entire pattern 2/	
			B8/-/-	
			009: Entire pattern 2/Entire pattern 3/	
			B9/-/-	
			010: Entire pattern 3/Entire pattern 4/-/-	
			011: Entire pattern 4/ Entire pattern 5/-/-/- 012: Entire pattern 5/ Entire pattern 6/-/-/-	
			013: Entire pattern $6/-/-/-$	
			254: Individual/Individual/-/-/-	
			* Default value "0" for Bar Code, "9" for	
			2D Code	
			* B7/8/9, Entire pattern 5/6: Available on	
		<b>D</b> .	only MD-U1000 series	
		<b>B</b> : 000 to	Finder 000: No	
		002/255	001: F1	
_		002,200	002: F2	
Para	meter		255: =Cell	
			* Fixed value of "0" when other than QR	
			Code AND B is 0 to 2	
		C:	* Default value "0" Alignment	
		000 to	000: No	
		002/255	001: A1	
			002: A2	
			255: =Cell	
			* Fixed value of "0" when other than DataMatrix AND C is 0 to 2	
			* Default value "0"	
		<b>D</b> : 000 to 008	Cell (QR Code/DataMatrix)	
			000: None/None	
			001: M1/C1	
			002: M2/C2	
			003: M3/C3 004: M4/C4	
			004. M4/C4 005: M5/C5	
			006: M6/C6	
			007: M7/C7	
			008: M8/C8	
			* Default value "0"	
		<i>E</i> : 001 to 003	Cell marking order	
			001: Continuous 002: Skip 1 cell	
			002: Skip 1 cells	
			*A: Fixed value of "1" when 8 to 11	
		<b>F</b> : 001 to 100	Cell marking count (times)	
			*A: Fixed value of "1" when 8 to 11	
			* Default value "1"	

Reference, • This command can be sent when the type of block (BlockType) is "09: Barcode/2D code" and the format setting of the barcode or 2D code related settings (CodeSetting) is the block No. of "2: Overprinting."

• "D: 0" cannot be set when "B: 0/255."

"D: 0" cannot be set when "C: 0/255."

# 3. Barcode/2D code overprinting fill parameters (Change/Request)

(Change/Request)			
Com	mand	MultiPassFillParam	neters
Description		code overprinting se	inting order in the barcode/2D tting and changes/requests the line interval setting and shrink
Targ	et	PRG=0000 to 1999,	BLK=000 to 255,OLP=0 to 9
WX Command		WX,PRG= <b>0000</b> ,BLK meters= <b>A</b> , <b>B</b> <sub>[CR]</sub>	= <b>000</b> ,OLP= <b>0</b> ,MultiPassFillPara
	Response	WX,OK [CR]	
RX	Command	RX,PRG <b>=0000</b> ,BLK <b>=000</b> ,OLP <b>=0</b> ,MultiPassFillPara meters [CR]	
	Response	RX,OK, A, B [CR]	
Para	meter	<b>A:</b> 0.000 to 1.000 /9.999	Fill interval (mm) * Fixed value of "9.999" if the common block marking parameter is referenced * Default value "Normal: 0.06"/"Wide: 0.08"/"Small: 0.03"
		<b>B:</b> 2D code: -2.500 to 02.500 Barcode: -5.000 to 05.000	Shrink fill (mm) * Default value "0"

Reference, • This command can be sent when the type of block (BlockType) is "09: Barcode/2D code" and the format setting of the barcode or 2D code related settings (CodeSetting) is the block No. of "2: Overprinting."

#### 4. Quality level of barcode/2D code overprinting (Change/Request)

	(Change/Reduest)		
Command		MultiPassQualityLevel	
Description		In barcode/2D code overprinting settings, specify the overprinting order and change/request the quality level.	
Target		PRG=0000 to 19	99,BLK=000 to 255,OLP=0 to 9
WX Command			BLK= <b>000</b> , sQualityLevel= <b>A</b> <sub>[CR]</sub>
	Response	WX,OK [CR]	
RX Command		RX,PRG=0000,BLK=000,OLP=0, MultiPassQualityLevel ICR1	
	Response	RX,OK, <b>A</b> [CR]	
Parameter		<b>A</b> : 00 to 06	Quality Level 00: Top speed 01: Speed priority 02: Standard 03: High quality 04: Top quality 05: Customize 06: Top speed 2 * Default value "02"

Reference . • The top Speed 2 is used on MD-X1000/1500 series only.

#### 5. Approach of barcode/2D code overprinting (Change/Request)

Com	nmand	MultiPassApproach		
Description		In barcode/2D code overprinting settings, specify the overprinting order and change/request the approach.		
Target		PRG=0000 to 1999,BLK=000 to 255,OLP=0 to 9		
wx	X Command WX,PRG=0000,BLK=000, OLP=0,MultiPassApproach=A <sub>ICR1</sub>			
	Response	WX,OK ICRI		
RX	Command	RX,PRG= <b>0000</b> ,BLK= <b>000</b> ,OLP= <b>0</b> ,MultiPassApproac h <sub>[CR]</sub>		
	Response	RX,OK,A [CR]		
Parameter		A:Normal/Wide:         Approach (mm)           0.000 to 5.000,         * Default value "0.500"           Small:         0.000 to 2.500		

Reference, • This command is enabled when the quality level of barcode/2D code overprinting (MultiPassQualityLevel) is "05: Customize".

# 6. Space approach of barcode/2D code overprinting (Change/Request)

	(onunge/request)			
Con	Command MultiPassSpaceApproach		Approach	
Description		In barcode/2D code overprinting settings, specify the overprinting order and change/request the		
		space approach.	0	
Targ	jet	PRG=0000 to 19	99,BLK=000 to 255,OLP=0 to 9	
	Command		BLK=000,OLP=0,MultiPassSpaceA	
wx	Command	pproach=A [CR]		
	Response	WX,OK [CR]		
	Command	RX,PRG=0000,BLK=000,OLP=0,MultiPassSpaceA		
RX	Command	pproach <sub>ICR1</sub>		
Response RX,OK,A [CR]				
Dorr	amotor	A:0.000 to 5.000	Space approach (mm)	
Parameter			* Default value "0.250"	
R	$\fbox{Reference}_{\Gamma}$ • This command is enabled when the quality level of			

barcode/2D code overprinting (MultiPassQualityLevel) is "05: Customize".

# 7. Curve correction of barcode/2D code overprinting (Change/Request)

•	(			
Command		MultiPassCurveCorrection		
Description		In barcode/2D code overprinting settings, specify the overprinting order and change/request the curve correction.		
Target			999,BLK=000 to 255,OLP=0 to 9	
wx	wx Command WX,PRG=0000,BLK=000,OLP=0 to MultiPassCurveCorrection=A <sub>(CR)</sub>			
	Response	WX,OK [CR]		
RX Command		RX,PRG= <b>0000</b> ,BLK= <b>000</b> ,OLP= <b>0</b> to <b>9</b> , MultiPassCurveCorrection <sub>[CR]</sub>		
	Response	RX,OK,A [CR]		
Parameter		<b>A</b> :0/1	Curve correction 0: Disabled 1: Enabled * Default value "0"	

 $Reference_{\Gamma}$  • It cannot be used on the MD-F3200/5200 series.

#### Jump speed of barcode/2D code overprinting (Change/Request)

(	(Change/Request)		
Com	mand MultiPassJumpSpeed		Speed
		In barcode/2D co	ode overprinting settings, specify
Des	cription	the overprinting	order and change/request the jump
		speed.	
Targ	jet	PRG=0000 to 19	999,BLK=000 to 255,OLP=0 to 9
	Command		BLK= <b>000</b> ,OLP= <b>0 to 9</b> ,
wx	Command	MultiPassJumpS	Speed=A [CR]
	Response	WX,OK [CR]	
	Commond	RX,PRG=0000,E	3LK= <b>000</b> ,OLP= <b>0 to 9</b> ,
RX	Command	MultiPassJumpSpeed [CR]	
	Response	RX,OK, <b>A</b> <sub>[CR]</sub>	
		<b>A:</b> 0/1/2	Jump speed
			0: Top Speed
Para	ameter		1: High Speed
			2: Medium Speed
			* Default value "0"

Reference ... 
 This command is enabled when the quality level of barcode/2D code overprinting (MultiPassQualityLevel) is not "05: Customize".

# 9. Wait time for start marking of barcode/2D code overprinting (Change/Request)

Command		MultiPassBlockMarkingDelayTime	
Description		In barcode/2D code overprinting settings, specify	
		the overprinting order and change/request the wait	
		time for start marking.	
Target		PRG=0000 to 19	99,BLK=000 to 255,OLP=0 to 9
	Command	WX,PRG=0000,BLK=000,OLP=0 to 9,	
WX		MultiPassBlockMarkingDelayTime=A [CR]	
	Response	WX,OK [CR]	
	Command	RX,PRG=0000,BLK=000,OLP=0 to 9,	
RX		MultiPassBlockMarkingDelayTime [CR]	
	Response	RX,OK, <b>A</b> <sub>[CR]</sub>	
Parameter		A:00000.0 to	Wait time for start marking (ms)
		65000.0	* Default value "0"

# 3-9 3D shape setting

#### 1. 3D shape setting (Change/Request)

Command		3DShape	
Description		Changes/requests the 3D shape setting	
		enable/disable and the 3D shape No. to be pasted.	
Target		PRG=0000 to 1999, BLK=000 to 255	
Command		WX,PRG=0000,E	3LK= <b>000</b> ,3DShape= <b>A</b> , <b>B</b> <sub>[CR]</sub>
wx	Response	WX,OK [CR]	
RX	Command	RX,PRG=0000,BLK=000,3DShape [CR]	
RX	Response	RX,OK, <b>A</b> , <b>B</b> <sub>[CR]</sub>	
		<b>A:</b> 0/1	3D shape setting
			0: XY Plane
			1: 3D Shape
Parameter			* Default value "0"
		<b>B</b> : 000 to 255	3D shape No.
			*A: Fixed value of "0" when 0
			* Default value "0"

Reference + This command can be sent to a block No. having the block type (BlockType) of other than "04: Fixed point".

### 2. 3D shape type (Change/Request)

0				
Command		3DShapeType		
Description		Specifies the 3D shape No. and creates a new or		
Dest	Inpuon	requests a 3D shape type.		
Target		PRG=0000 to 1999, 3DS=000 to 255		
wx	Command	WX,PRG=0000,3	BDS= <b>000</b> ,3DShapeType= <b>A</b> [CR]	
***	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,3DS=000,3DShapeType		
~~	Response	RX,OK,A <sub>[CR]</sub>		
		A: -01/000 to	3D Shape	
		006/020	-01: Z map	
			000: Slope	
			001: Inside cylinder	
			002: Outside cylinder	
Para	meter		003: Inside cone	
			004: Outside cone	
			005: Inside hemisphere	
			006: Outside hemisphere	
			020: XY Plane	
			* Default value "20"	

Reference You cannot change a 3D shape No. for which a 3D shape has already been set. The 3D shape setting information is initialized when the block associated with the 3D shape No. is removed.

• Therefore, associate the block using the 3DShape command following the 3DShapeType.

## 3. 3D shape position (Change/Request)

3. 3D shape position (Change/Request)				
Command 3DShapePosition				
Description		Specifies the 3D shape No. and changes/requests the $X/X/X$ specifies the 3D shape No. and changes/requests the		
Target		X/Y/X coordinates and X/Y/Z rotation angles. PRG=0000 to 1999, 3DS=000 to 255		
WX PRG=0000 3DS=000 3DShapePosition=A B				
WX Command		, <b>F</b> <sub>ICRI</sub>	or conton 71,2,0,2,2	
	Response	WX,OK <sub>[CR]</sub>		
RX	Command	RX,PRG=0000,3DS=000,3DShapePosition [CR]		
101	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> , <b>F</b> <sub>[CR]</sub>		
		A: Depends on the area size and	X coordinate (mm) * Default value "0"	
		block type - The block type is other than arc	* Detault value "0"	
		character		
		Normal(X):0000.200 to 0480.000		
		Other model: 04"X coordinate" of		
		"Appendix-2 Model-Specific Input		
		Value List" (Page49).		
		<ul> <li>The block type is arc character</li> <li>-9999.99 to 09999.99</li> </ul>		
		<b>B</b> : Depends on the area size, block	Y coordinate (mm)	
		type and 3D shape type	* Default value "0"	
		- The block type is other than arc		
		character and 3D shape is other than		
		cone		
		Normal(X):0000.200 to 0480.000 Other model: 印"Y coordinate" of		
		"Appendix-2 Model-Specific Input		
		Value List" (Page49).		
		- The block type is other than arc		
		character and 3D shape is cone		
		Normal:0000.000 to 0062.500(X/F/U), 0000.000 to		
		0060.000(Z)		
		Wide:0000.000 to 0165.000(X/U),		
		0000.000 to 0150.000(F/Z)		
		Small:0000.000 to 0025.000		
		- The block type is arc character -9999.99 to 09999.99		
		<b>C</b> : Depends on the area size and 3D	Z coordinate (mm)	
		shape type	* Default value "0"	
		- The 3D shape is cylinder, cone or		
Para	ameter	sphere		
		Normal: -261.000 to 0261.000(X/F/U/Z)		
		-201.000 (0 0201.000(X/170/2)		
		Wide:		
		-621.000 to 0621.000		
		(X/F/U/Z)		
		Small: -115.000 to 0115.000 (X/F/U),		
		-102.000 to 0102.000(Z)		
		- The 3D shape is slope		
		Normal:		
		-083.500 to 0083.500(X/F/U), -081.000 to 0081.000(Z)		
		-081.000 to 0081.000(2) Wide:		
		-186.000 to 0186.000(X/F/U),		
		-171.000 to 0171.000(Z)		
		Small: -040.000 to 0040.000(X/F/U),		
		-027.000 to 0027.000(Z)		
		- The 3D shape is Z-map		
		Normal:		
		-125.000 to 0125.000(X/F/U)		
		-120.000 to 0120.000(Z)		
		Wide:		
		-330.000 to 0330.000(X/U) -300.000 to 0300.000(F/Z)		
		Small: -050.000 to 0050.000		
		<b>D:</b> -180.000 to 0180.000	X rotation angle (°)	
			* Default value "0"	
		<i>E</i> : -180.000 to 0180.000	Y rotation angle (°)	
		<b>E:</b> 180,000 to 0190,000	* Default value "0"	
		F: -180.000 to 0180.000	Z rotation angle (°) * Default value "0"	

Reference • This command can be sent to a block No. having the 3D shape setting (3DShape) of "1: 3D Shapes".

• Specify the target specifier 3DS based on the 3D shape No. of the 3D shape setting (3DShape).

# 4. Diameter of cylinder shape (Change/Request)

4. Diameter of cylinder shape (Change/Request)				
Command CylinderDiameter				
Description		Specifies the 3D shape No. and changes/requests the diameter of a cylinder shape.		
Target		PRG=0000 to 1999, 3DS=000 to 255		
wx	Command	WX,PRG=0000,3DS=000,CylinderDiameter=A ICRI		
VVA	Response	WX,OK <sub>[CR]</sub>		
RX	Command	RX,PRG=0000,3DS=000,CylinderDiameter [CR]		
КЛ	Response	RX,OK,A <sub>[CR]</sub>		
Parameter		A: Depends on the area size Normal(X): 0000.200 to 0480.000 Other model: "Cylinder diameter" of "Appendix-2 Model-Specific Input Value List" (Page49).	Cylinder diameter (mm) * Default value "Normal/Wide: 40"/"Small: 20"	
Reference · This command can be sent to a block No. having the 3D shape setting (3DShape) of "1: 3D Shapes" AND the 3D shape type (3DShapeType) of "01/02: Cylinder". • Specify the target specifier 3DS based on the 3D shape No.				

of the 3D shape setting (3DShape).

### 5. Cone shape size setting (Change/Request)

Com	nmand	ConeSize		
Description		Specifies the 3D shape No. and changes/requests the		
		various sizes of a cone shape.		
Targ		PRG=0000 to 1999, 3DS=000		
wx	Command	WX,PRG=0000,3DS=000,Cone	eSize= <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> [CR]	
	Response	WX,OK <sub>[CR]</sub>		
RX	Command	RX,PRG=0000,3DS=000,Cone	Size <sub>ICR1</sub>	
INA.	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> <sub>[CR]</sub>		
		A: Depends on the area size Normal(X): 0000.200 to 0480.000 Other model: <sup>III</sup> "Bottom diameter of cone" of "Appendix-2 Model-Specific Input Value List" (Page49).	Bottom diameter (mm) * Default value "Normal/Wide: 40"/"Small: 20"	
Parameter		<b>B</b> : 0/1	Set with bus angle 0: Disabled 1: Enabled * Default value "0"	
		C: Depends on the area size Normal(X):0000.200 to 0480.000 Other model: I <sup>III</sup> "Top diameterr of cone" of "Appendix-2 Model-Specific Input Value List" (Page49).	Top diameter (mm) * Default value "Normal/Wide: 20"/"Small: 10"	
		D: Depends on the area size Normal(X):0000.100 to 125.000 Other model: <sup>[1]</sup> "Cone height" of "Appendix-2 Model-Specific Input Value List" (Page49).	Height (mm) * Default value "Normal/Wide: 20"/"Small: 10"	
		<i>E</i> : -85.000 to 085.000	Bus angle (°) * Default value "0"	

Reference This command can be sent to a block No. having the 3D shape setting (3DShape) of "1: :3D shape AND the 3D shape type (3DShapeType) of "3/4: Cone".

- Specify the target specifier 3DS based on the 3D shape No. of the 3D shape setting (3DShape).
- The bus angle cannot be set when the specification is disabled at the bus angle. The top diameter and height cannot be set when the specification is enabled at the bus angle.

#### 6. Diameter of sphere shape (Change/Request)

Command		SphereDiameter		
Description		Specifies the 3D shape No. and changes/requests the		
Des	cription	diameter of a sphere shape.		
Target		PRG=0000 to 1999, 3DS=000 to 255		
wx	Command	WX,PRG=0000,3DS=000,SphereDiameter=A [CR]		
VVA	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,3DS=000,SphereDiameter [CR]		
RA	Response	RX,OK, <b>A</b> <sub>[CR]</sub>		
		A: Depends on the area size	Diameter (mm)	
		Normal(X):	* Default value "20"	
		0000.200 to 0480.000		
Para	ameter	Other model:		
		<sup><sup>□</sup> "Sphere diameter" of</sup>		
		"Appendix-2 Model-Specific		
		Input Value List" (Page49).		

Reference + This command can be sent to a block No. having the 3D shape setting (3DShape) of "1: 3D Shapes" AND the 3D shape type (3DShapeType) of "05/06: Sphere".

• Specify the target specifier 3DS based on the 3D shape No. of the 3D shape setting (3DShape).

#### 7. Position on 3D shape (Change/Request)

~					
		3DSurfacePosition			
Description		Changes/requests the X/Y/ $\theta$ positions on the 3D shape.			
Target PRG=0000 to 1999, BLK=000 to 255					
WX Command		WX,PRG=0000,BLK=000,3DSurfacePosition=A,B,C [CR]			
RX			acePosition [CR]		
	Response				
Response WX,OK [CR]		block type - The block type is other than arc character Normal(X):-062.500 to 0062.500 Other model: Ш"X coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49). - The block type is arc character -9999.99 to 09999.99 <b>B</b> : Depends on the area size, block type and 3D shape type - The block type is other than arc character and 3D shape type - The block type is other than arc character and 3D shape is other than cone Normal(X/F): -062.500 to 0062.500(X/F/U), -060.500 to 0165.000(X/U), -150.000 to 0165.000(X/U), -150.000 to 0165.000(Y/Z) Small: -025.000 to 0025.000(U/Z) - The block type is other than arc character and 3D shape is cone Normal: 0000.000 to 0062.500(X/F/U), 0000.000 to 0165.000(Z) Wide: 0000.000 to 0165.000(X/U), 0000.000 to 0150.000(F/Z) Small: 0000.000 to 0150.000(F/Z) Small: 0000.000 to 0025.000(X/Z) - The block type is arc character -9999.99 to 09999.99	X coordinate (mm) on 3D shape * Default value "0" Y coordinate (mm) on 3D shape * Default value "0" θ angle (°) on 3D shape * Default value "0"		

Reference • This command can be sent to a block No. having the 3D shape setting (3DShape) of "01: 3D Shapes".

- When the type of 3D shape (3DShapeType) is a cylinder or cone (001 to 004), the X coordinate on the 3D shape cannot be set.
- When the type of 3D shape (3DShapeType) is other than a cylinder or cone (001 to 004), the  $\theta$  angle on the 3D shape cannot be set.

#### 8. Cone setting (Change/Request)

Command		ConeSetting	
Description		Changes/requests how to paste, layout, set the	
Dest	Inpuon	character angle s	pace and open angle of a cone.
Target		PRG=0000 to 19	99, BLK=000 to 255
WX Command		WX,PRG=0000,E	BLK= <b>000</b> ,ConeSetting= <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> <sub>[CR]</sub>
WVA	Response	WX,OK [CR]	
RX	Command	RX,PRG=0000,B	LK=000,ConeSetting [CR]
Rλ	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b>	CR]
		<b>A:</b> 0/1	Char. Frame
			0: Use fixed length
			1: Use fixed angle
			* Default value "0"
		<b>B:</b> 1/2	Layout
			1: Angular interval
			2: Distribute angle
Para	meter		3: Character pitch
			* Default value "1"
		C: 000.000 to	Character angle space (°)
		180.000	* Fixed value of "10" when B is 2/3
			* Default value "10"
		<b>D</b> : 000.000 to	Open angle (°)
		180.000	Fixed value of "120" when B is 1/3
			* Default value "120"

• B: 3 (Character Pitch) can be set only in the case of TrueTypeFont.
# 3-10 Matrix setting

# 1. Matrix row & column setting (Change/Request)

Con	nmand	MatrixSetting		
Description		Changes/requests the number of rows/columns and		
		marking direction of a m	atrix.	
Target		PRG=0000 to 1999		
wx	Command	WX,PRG=0000,MatrixS	etting=A,B,C <sub>[CR]</sub>	
WX	Response			
RX	Command	RX,PRG=0000,MatrixSetting [CR]		
RX	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> <sub>ICR1</sub>		
		A: 001 to 255	Line count	
		<b>B</b> : 001 to 255	Number of columns	
		<b>C:</b> 1/2/4/5	Marking direction	
Dar	ameter		1: Horizontal	
raidilletei			2: Vertical	
			4: Horizontal (Alternate)	
			5: Vertical (Alternate)	
			* Default value "1"	

### 2. Matrix size setting (Change/Request)

Command		MatrixSize		
		Changes/requests the height, height specification		
Description		method, width, and width spec	ification method of a	
		matrix.		
Targ	get	PRG=0000 to 1999		
wx	Command	, , ,	<b>B</b> , <b>C</b> <sub>[CR]</sub>	
	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,MatrixSize [CR]		
112	Response	RX,OK, <i>A</i> , <i>B</i> , <i>C</i> <sub>[CR]</sub>		
		<i>A</i> : 0/2/3 <i>B</i> : Depends on the area size Normal(X): 000.000 to 125.000 Other model:	Height specification method 0: Cell height 2: Maximum distance 3: Matrix height * Default value "0" Height (mm) * Default value "15" for Normal/Wide, and "5" for	
Para	ameter	"Matrix Height/Width" of "Appendix-2 Model-Specific Input Value List" (Page49). <b>C:</b> 0/2/3	Small Width specification	
			method 0: Cell width 2: Maximum distance 3: Matrix width * Default value "0"	
		D: Depends on the area size Normal(X): 000.000 to 125.000 Other model: □"*Matrix Height/Width" of "Appendix-2 Model-Specific Input Value List" (Page49).	Width (mm) * Default value "15" for Normal/Wide, and "5" for Small	

# 3. Matrix cell reference point (Change/Request)

nmand	CellReferencePoint			
cription	Changes/requests the cell reference point of a matrix.			
et	PRG=0000 to 1999			
Command	WX,PRG=0000,CellF	ReferencePoint=A [CR]		
Response	WX,OK [CR]			
Command	d RX,PRG=0000,CellReferencePoint			
Response	RX,OK, <b>A</b> <sub>ICRI</sub>			
	A: 02 to 06	Cell base point		
		02: Center		
	03: Lower left			
meter	04: Lower right			
		05: Upper left		
		06: Upper right		
		* Default value "02"		
	cription et Command Response Command Response	cription         Changes/requests the PRG=0000 to 1999           command         WX,PRG=0000,CellF           Response         WX,OK [CR]           Command         RX,PRG=0000,CellF           Response         RX,OK,A [CR]           A: 02 to 06         06		

# 4. Cell individual setting (Change/Request)

Con	nmand	MatrixCell		
Description		Specifies the matrix cell and changes/requests the marking enable/disable, X/Y/Z coordinate correction, $\theta$ angle correction and marking start wait time.		
Targ	jet	PRG=0000 to 1999,CEL=00001		
WX Command		WX,PRG=0000,CEL=00001,MatrixCell=A,B,C,D,E,F		
	Response	WX,OK [CR] RX,PRG= <b>0000</b> ,CEL= <b>00001</b> ,Mati	rivCall	
RX	Command	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> , <b>E</b> , <b>F</b> <sub>ICR1</sub>		
Response		<b>A</b> : 0/1	Marking flag 0: Do not Mark 1: Mark * Default value "1"	
		B: Depends on the area size Normal(X):-062.500 to 0062.500 Other model: <sup>[[]</sup> "X coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	X coordinate (mm) Default value "0"	
Para	ameter	C: Depends on the area size Normal(X):-062.500 to 0062.500 Other model: <sup>CD</sup> "Y coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	Y coordinate (mm) Default value "0"	
		D: Depends on the area size Normal(X):-021.000 to 0021.000 Other model: <sup>[1]</sup> "Z coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	Z coordinate (mm) Default value "0"	
		<i>E</i> : -180.000 to 0180.000	θ angle (°) Default value "0"	
		<b>F</b> : 00000.0 to 65000.0	Wait time for start marking (ms) * Default value "0"	

# 5. Cell marking flag (Change)

Command		MatrixCellEr	nable		
Description		Changes the marking flag of matrix cells in binary.			
Targ	get	PRG=0000 to	o 1999,CEL=00001 to 65025		
	Command	WX,PRG= <b>00</b>	WX,PRG=0000,CEL=00001,MatrixCellEnable=A,BBB-		
wx		[CR]			
	Response	WX,OK [CR]			
DV	Command	No			
RX	Response	NO			
Parameter		<b>A</b> : 0/1/2	Reset the marking flag 0: Set the marking flag of all cells to OFF 1: Set the marking flag of all cells to ON 2: Do not change other than the specified cells		
		<b>B</b> : 0/1	Marking flag 0: Do not Mark 1: Mark * You can change the marking flag of continuous cells in a batch by sending this parameter in multiple digits.		
To change the marking flag of multiple colls in a batch, cond					

Reference · To change the marking flag of multiple cells in a batch, send parameter B in multiple digits.

To set cell No.10 to ON, No.11 to OFF, No.12 to ON and all other cells to OFF, send the command as described below. WX,PRG=0000,CEL=00010,MatrixCellEnable=0,101 [CR]

# 6. Matrix position setting (Change/Request)

A Materia Desition				
Con	nmand	MatrixPosition		
Description		Changes/requests the reference point and X/Y		
	•	coordinates of a matrix.		
Targ	get	PRG=0000 to 1999		
wx	Command	WX,PRG=0000,MatrixPosition=	<b>A</b> , <b>B</b> , <b>C</b> <sub>[CR]</sub>	
***	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,MatrixPosition [CF	र।	
~~	Response	RX,OK, <i>A</i> , <i>B</i> , <i>C</i> <sub>[CR]</sub>		
Response		<b>A</b> : 00 to 08	Base point 00: Left edge 01: Right edge 02: Center 03: Lower left 04: Lower right 05: Upper left 06: Upper right 07: Top 08: Bottom * Default value "2"	
Parameter		B: Depends on the area size Normal(X):-062.500 to 0062.500 Other model: □"X coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49). C: Depends on the area size Normal(X):-062.500 to 0062.500 Other model: □"Y coordinate" of "Appendix-2 Model-Specific Input Value List" (Page49).	X coordinate (mm) * Default value "0" Y coordinate (mm) * Default value "0"	

# 7. Count using invalid marking cells (Change/Request)

Com	mand	InactiveCellCount	
		Changes/requests the setting of whether or not to	
Desc	cription		marking cells when marking a
		counter in a matrix.	
Target		PRG=0000 to 19	
wx	Command WX,PRG=0000,InactiveCellCount=A [CR]		nactiveCellCount=A [CR]
Response		WX,OK <sub>[CR]</sub>	
RX	Command	RX,PRG=0000,InactiveCellCount [CR]	
~~	Response	RX,OK,A <sub>[CR]</sub>	
Parameter		<b>A:</b> 0/1	Count the invalid marking cells
			0: Disabled
			1: Enabled
			* Default value "0"

# 3-11 Group/Counter setting

# 1. Group setting (Change/Request)

n ereup eetting (entingentequeet)				
Command		GroupOffset		
		Specifies the group and changes/requests the X/Y		
Dese	cription	coordinate correction, θ angle corr	ection and marking	
		enable/disable setting.	-	
Targ	jet	PRG=0000 to 1999,GRP=000 to 2		
wx	Command	WX,PRG=0000,GRP=000,GroupC	Offset=A, B, C, D [CR]	
VVX	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,GRP=000,GroupO	ffset <sub>ICR1</sub>	
RA	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> <sub>[CR]</sub>		
		A: Depends on the area size	Shift X(mm)	
		Normal(X):-062.500 to 0062.500	* Default value "0"	
		Other model: <sup>III</sup> "X coordinate" of		
		"Appendix-2 Model-Specific Input		
		Value List" (Page49).		
		B: Depends on the area size	Shift Y(mm)	
Dana		Normal(X):-062.500 to 0062.500	* Default value "0"	
Para	ameter	Other model: <sup>III</sup> "Y coordinate" of		
		"Appendix-2 Model-Specific Input		
		Value List" (Page49).		
		C: -180.000 to 0180.000	Shift θ(mm)	
		<b>D</b> : 0/1	Marking flag	
			0: Disabled	
			1: Enabled	

Reference, • You can only create new groups using Marking Builder 3. The group number assigned when you created a group in Marking Builder 3 will be the number of the target specifier GRP.

# 2. Counter setting (Change/Request)

Command CounterSetting				
Description		Specifies the counter No. and changes/requests the		
Description		various counter s	settings.	
Target		PRG=0000 to 19	999,CTR=0 to 9/A to J,	
WX Command			CTR=0,CounterSetting=A,B,C,D,E,	
		<b>F</b> , <b>G</b> , <b>H</b> , <b>I</b> <sub>[CR]</sub>		
	Response	WX,OK [CR]		
RX	Command	RX,PRG=0000,CTR=0,CounterSetting [CR]		
	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b> , <b>D</b> ,		
		A: 00000 to	Step	
		10000	* Default value "1"	
		<b>B:</b> 0/1	Enabling the default value	
			0: Disabled	
			1: Enabled	
			* Default value "0"	
		<b>C</b> : 000000000 to	Default value	
		4294967295	*B: Fixed value of "0" when 0	
			* Default value "0"	
		<b>D</b> : 000000000 to Leading value		
		4294967295 * Default value "0"		
		<i>E</i> : 000000000 to		
		4294967295	* Default value "4294967295"	
		<i>F</i> : 000000000 to	Marking count	
Para	meter	4294967295	* Default value "1"	
		<b>G</b> : 0 to 4	Reset timing	
			0: Trigger	
			1: I/O	
			2: Power on	
			<ol><li>When switching the program No.</li></ol>	
			4: When the date changes	
			5: When the shift code is switched	
			* Default value "1"	
		<b>H:</b> 0/1	Count timing	
			0: Trigger	
			1: Each matrix cell/group/marking	
			* Default value "0"	
		<i>I</i> : 2 to 36	Base	
			* Default value "10"	

Reference · The target specifier PRG can be omitted if you are specifying a common counter.

# 3-12 Operation time

# 1. Request on controller operating time

Command		OperatingTime	
Description		Requests the operating time of the laser marker.	
Targ	jet	no	
wx	Command	no	
***	Response		
Command RX,OperatingTime (CR)		[CR]	
RX	Response	RX,OK,A [CR]	
Parameter		A:00000~999999	Cumulative operation time (h)

### 2. Request on laser exited time

Con	nmand	LaserOperatingTime	
Description		Requests the laser exited time. It is available on MD-U1000 and ML-Z9600 series only.	
Targ	get	no	
wx	Command	no	
**^	Response		
RX	Command	RX, LaserOperatingTime [CR]	
RX	Response	RX,OK, <b>A</b> <sub>(CR)</sub>	
Parameter		<b>A</b> : 00000~99999	Laser exited time (h)

### 3. Request on scanner operating time

Command		ScannerOperatingTime	
Description		Requests the scanner operating time It is available on MD-U1000 and ML-Z9600 series only.	
Targ	get	no	
wx	Command	no	
VVA	Response		
RX	Command	RX, ScannerOperatingTime [CR]	
RX	Response	RX,OK, <b>A</b> <sub>[CR]</sub>	
Parameter		A: 00000~99999	Scanner operating time (h)

# 4. Request on number of shutter operations

Command		ShutterOperatingCount	
Description		Requests the number of shutter operations. It is available on MD-U1000 and ML-Z9600 series only.	
Target		no	
wx	Command	no	
**^	Response		
RX	Command	RX, ShutterOperatingCou	Int [CR]
Response RX,OK,A [CR]			
Parameter		<b>A</b> :00000000~4294967295	Number of shutter operations (times)

# 5. Request on number of contactor operations

Command ContactorOperatingCount		int	
Description		Requests the number of contactor operations. It is available on MD-U1000 series only.	
Target		no	
wx	Command	20	
VVX	Response	no	
RX	Command	RX, ContactorOperatingC	count <sub>[CR]</sub>
RA	Response	RX,OK,A [CR]	
Parameter		<b>A</b> :0000000~4294967295	Number of contactor operations (times)

### 6. Request on head temperature

Command		MarkingUnitTemperatu	re	
Description		Requests the head temp		
	•	It is available on MD-010	It is available on MD-U1000 series only.	
Targ	get	no		
wx	Command	no		
**^	Response			
RX Command Response		RX,MarkingUnitTempera	ture <sub>[CR]</sub>	
		RX,OK, <b>A</b> [CR]		
Parameter		<b>A:</b> -999.9~0999.9	Head temperature (°C)	

# 7. Request on controller temperature (°C)

Command		ControllerTemperature	
Description		Requests the controller temperature. It is available on MD-U1000 series only.	
Target		no	-
wx	Command	20	
VVA	Response	no	
RX Command Response		RX,ControllerTemperatur	e (CR)
		RX,OK, <b>A</b> [CR]	
Parameter		<b>A:</b> -999.9~0999.9	Controller temperature (°C)

# 8. Request on the result of laser power calibration

Command		LaserPowerCalibrationResult	
Description		Requests the result of la	ser power calibration.
		It is available on MD-U1000 series only.	
Targ	get	no	
wx	Command	20	
VVX	Response	no	
RX	Command	RX,LaserPowerCalibrationResult [CR]	
RX	Response	RX,OK, <b>AB</b> [CR]	
		<b>A:</b> 0/1	Existence of calibration
			execution
Parameter			0: no
			1: yes
		<b>B:</b> 000.00~999.99	Calibration result (W)

#### 9. Cumulative marking count 1 and 2 (change/request)

Command		CumulativeMarkingCount	
Description		Changes and request the and 2.	cumulative marking count 1
Targ	get	no	
wx	Command	<b>J</b>	
VVA	Response		
RX	Command	RX,CumulativeMarkingCount [CR]	
RA	Response	RX,OK, <b>A</b> , <b>B</b> [CR]	
Parameter		<b>A</b> :0000000~4294967295	Cumulative marking count 1 (time)
		<b>B</b> :0000000~4294967295	Cumulative marking count 2 (times)

# 10. Request on replacing expiration of the dry agent for the head.

Con	nmand	DesiccantExpirationDate		
Description		the head.	replacing expiration of the dry agent for on MD-U1000 series only.	
Targ	get	no		
wx	Command	20		
VVA	Response	no		
RX Command		RX,DesiccantExpirationDate [CR]		
RA.	Response	RX,OK, <b>A</b> , <b>B</b> , <b>C</b>	[CR]	
		A:0000~2099	Replacing expiration of the dry agent:	
			year	
Dor	amotor	<b>B</b> :00~12	Replacing expiration of the dry agent:	
Parameter			month	
		<b>C:</b> 00~31	Replacing expiration of the dry agent:	
			date	

# 11. Request on number of open/close of safety shutter A

Command		SafetyShutterAOperatin	gCount
		Requests the number of c	open/close of safety shutter
Des	cription	A.	
		It is available on ML-Z9600 series only.	
Targ	get	no	
wx	Command	no	
VVA	Response	10	
RX	Command	RX,SafetyShutterAOperat	tingCount [CR]
Response		RX,OK, <b>A</b> [CR]	
Parameter		<b>A</b> :0000000~4294967295	Number of operations of
			safety shutter A (times)

# 12. Request on number of open/close of safety shutter B

Command		SafetyShutterBOperatin	gCount
		Requests the number of c	open/close of safety shutter
Des	cription	В	
		It is available on ML-Z9600 series only.	
Targ	get	no	
wx	Command	no	
VVA	Response	lio	
RX	Command	RX,SafetyShutterBOperat	tingCount [CR]
Response		RX,OK, <b>A</b> [CR]	
Parameter		<b>A</b> :0000000~4294967295	Number of operations of
			safety shutter B (times)

# 13. Request on laser oscillating tube temperature

Con	nmand	MarkingLaserOscillator	Temperature
Description		Requests the laser oscillating tube temperature. It is available on ML-Z9600 series only.	
Target		no	
wx	Command	20	
**^	Response	no	
RX Command RX, MarkingLaserOscillatorTemperatur		torTemperature [CR]	
КA	Response	RX,OK, <b>A</b> [CR]	
Parameter		<b>A:</b> -999.9~0999.9	Laser oscillating tube temperature (°C)

# 3-13 Laser power measurement

# 1. Laser power measurement

Con	nmand	LaserPowerCheck		
Description		for the measurement marking point is not	asures the laser power. It takes about 10 seconds the measurement. The shutter closes, and the rking point is not irradiated. a available on MD-U1000 series only.	
Targ	get	no		
wx	Command	WX,LaserPowerCheck= <b>A</b> , <b>B</b> [CR]		
***	Response	WX,OK, C [CR]	(CR)	
RX	Command	no		
ĸл	Response			
Parameter		<b>A:</b> 000.0~100.0	Laser Power (%)	
		<b>B:</b> 000/040~400	Pulse frequency (kHz)	
		<b>C</b> :000 00~999 99	Output power (W)	

# 4. Applied Functions

This chapter provides information on omission of parameters, convenient command usages and how to create new settings using only commands.

# 4-1 Variable-length support

The unwanted "0" can be omitted when sending the setting values to the laser marker using the Write command.

Omission of the command for changing the currently running program No. to "1"

 Command
 WX,ProgramNo=0001
 CRI

 Response
 WX,OK
 CRI

 Change the program No. to variable-length
 Change the program No. to variable-length

 Command
 WX,ProgramNo=1
 ICRI

 Response
 WX,OK
 ICRI
 ICRI

Variable-length support complete

Omission of the command for changing the position correction values

Command	WX,AllPosition=-90.000,000.000,090.000,-062.500,0000 .000,21.000 [CR]	
Response	WX,OK [CR]	
Change the correction value to variable-length		

Command	WX,AllPosition=-90,0,90,-62.5,0,21 [CR]
Response	WX,OK <sub>[CR]</sub>
Variable length support complete	

Variable-length support complete

# 4-2 Omission of target specifiers

In the following cases, you can send the command omitting the target specifier.

# If the currently running program No. is the target

You can omit the target specifier if you are specifying the currently running program No. using the "PRG" target specifier.

Omission of the command for changing the title of the currently running program No.0001 to "ABC"

Command	WX,PRG=0001,Title=ABC <sub>[CR]</sub>
Response	WX,OK <sub>[CR]</sub>
You can omit "PRG" as this is a currently running program No.	

Command	WX,Title=ABC <sub>[CR]</sub>
Response	WX,OK <sub>[CR]</sub>
Omission complete	

# If block No.000 is the target

You can omit the target specifier if you are specifying block No. 000 using the "BLK" target specifier.

Omission of the command for changing the block No.000 string of the currently running program No.0001 to "ABC"

Command	WX,PRG=0001,BLK=000,CharacterString=ABC [CR]
Response	WX,OK <sub>ICR]</sub>
You can omit "BLK" for block No.000.	

Command	WX,PRG=0001,CharacterString=ABC <sub>[CR]</sub>
Response	WX,OK <sub>[CR]</sub>
You can om	it "PRG" as this is a currently running program No.

Command	WX,CharacterString=ABC [CR]
Response	WX,OK <sub>ICR1</sub>
Omission complete	

# 4-3 Omission of parameters

If you only wish to change some parameters using a command that have multiple parameters, you can send the command omitting those parameters you do not need to change.

Omission of the command changing only the C: Day setting value out of the six date/time setting parameters (A: Year, B: Month, C: Day, D: Hour, E: Minute, F: Second)

To change the current time setting of 2014/12/20/11: 38: 20 to

	2014/12/21/11: 38: 20	
	Command	WX,TimeSetting=2014,12,21,11,38,20 [CR]
	Response	WX,OK <sub>JCR1</sub>
Omit the unwanted parameters		

Command	WX,TimeSetting=,,21,,, <sub>[CR]</sub>
Response	WX,OK <sub>ICR1</sub>
Omission complete	

Reference • The omitted settings will retain their current status.

4

The number of separator commas remain unchanged.

#### 4-4 Sending of linked commands

You can link commands and send them together when sending commands to the same program No. for multiple times. Moreover, you can omit the already-specified target specifier when linking commands. Enter a target specifier only if you wish to re-specify the target in the middle of a command.

- Important You cannot link and send a command targeting two or more program No.
  - You cannot link and send commands that are related to "Operation/Current Value" or "Status/Unit Setup".

#### For WX command

To send the command with a linked WX command, link the command by adding "WX" only to the first command and removing "WX" from the second and subsequent commands.

Omission of the command for changing the block No.1 string of the currently running program No.0001 to "ABC", and the block No.2 string to "123"

1. Command	WX,PRG=0001,BLK=001,CharacterString=ABC [CR]
2. Response	WX,OK <sub>[CR]</sub>
3. Command	WX,PRG=0001,BLK=002,CharacterString=123 [CR]
4. Response	WX,OK <sub>[CR]</sub>

You can link the commands as they are changes in the same program No.

Command	WX,PRG=0001,BLK=001,CharacterString=ABC,PRG=0 001,BLK=002,CharacterString=123 <sub>[CR]</sub>
Response	WX,OK <sub>[CR]</sub>

You can omit the "PRG" on the end as the program No. are the same.

Command	WX,PRG=0001,BLK=001,CharacterString=ABC,BLK=0 02,CharacterString=123 [CR]
Response	WX,OK <sub>[CR]</sub>

You can omit "PRG" as this is a currently running program No.

Command	WX,BLK=001,CharacterString=ABC,BLK=002,Characte
	rString=123 <sub>[CR]</sub>
Response	WX,OK <sub>[CR]</sub>

You can omit "0s" as they are unnecessary for the parameters.

Command	WX,BLK=1,CharacterString=ABC,BLK=2,CharacterStri ng=123 [CR]	
Response	WX,OK [CR]	
Omission co	Omission complete	

ission complete

# For RX command

To send the command with a linked RX command, link the command by adding "RX" only to the first command and removing "RX" from the second and subsequent commands. A response is returned in the order of the requesting commands.

### Omission of the command for requesting the block No.1 (String: ABC) and No.2 (String: 123) string setting of the currently running program No. 0001

1. Command	RX,PRG=0001,BLK=001,CharacterString <sub>[CR]</sub>
2. Response	RX,OK,ABC [CR]
3. Command	RX,PRG=0001,BLK=002,CharacterString <sub>[CR]</sub>
4. Response	RX,OK,123 [CR]
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You can link the commands as they are requests in the same program No.

Command	RX,PRG=0001,BLK=001,CharacterString,PRG=0001,B
Command	LK=002,CharacterString [CR]
Response	RX,OK,ABC,123 [CR]
You can omit the latter "PPC" as the program No, are the same	

You can omit the latter "PRG" as the program No. are the same.

Command	RX,PRG=0001,BLK=001,CharacterString,BLK=002,Ch
Commanu	aracterString [CR]
Response	RX,OK,ABC,123 [CR]
You can omi	t "PRG" as this is a currently running program No.

ig p

Command	RX,BLK=001,CharacterString,BLK=002,CharacterString	
Response	RX,OK,ABC,123 <sub>[CR]</sub>	
You can omi	t "0s" as they are unnecessary for the parameters.	

Command	RX,BLK=1,CharacterString,BLK=2,CharacterString [CR]
Response	RX,OK,ABC,123 [CR]
Omission co	mplete

#### Linking the communication command (WXC command)

You can link and send commands by using WXC command. Commands relating to operation can also be linked. The response will return when all the command processing has been completed. If an error occurs on a command, commands before the error are executed but commands after the error are not. In case of linking the commands, put "WXC," at the beginning and link the commands with ",%,".

In case of changing a character string and then continue the marking

Command	WXC,WX,PRG=000,BLK=000,CharacterString=ABC,%, WX,StartMarking [CR]
Response	WXC,OK [CR]

Up to 128 commands can be linked up. The request commands (RX commands) cannot be used. When the request commands are linked, no error will occur as long as the commands are proccessed correctly, but the results of the requests do not return as a response.

#### When an error occurs in halfway of linking commands.

The following linking command that switches the marking program to No.10 after the recent program's marking is finished. The error response below returns if there is no marking program in No.10.

Command WXC,WX,StartMarking,%,WX,ProgramNo=10 [CR] Response WXC,NG,cmd\_index=002,E015,No Program Error [CR] cmd\_index: No. of the linking commands on which an error occurs. 000 indicates errors occur on WXC command. 001 or the subsequent number indicates errors occur on the linking commands.

#### 4-5 Creating new settings

Follow the workflow below if you are creating new settings using only a communication path.

(1) Starting the creation of a new program Declare a start of program creation on a non-registered

program No. using the following command:

Command		CreateProgram	
Description		No. The specified prog	rogram creation on a program ram No. will stop the until "EndProgram" is input.
Target		No	
WX Command		WX,CreateProgram=A [CR]	
Response		WX,OK [CR]	
RX Command		No	
RA	Response		
Parameter		A: 0000 to 1999	Specifies the Program No.

- program No., a program will be created with all parameters in their default values.
  - · By declaring "CreateProgram" on an existing program No., you can change the desired program parts using this program file as a base.
  - · If you wish to initialize the program contents every time you create a program, insert
  - "CreateProgramWithAllClear" into the command.
  - (2) Setting the required program and block information The command required to print a single block is described below.
    - Head orientation <sup>III</sup>"HeadDirection" (Page16) Block type <sup>III</sup> "Block Type"(Page21)

    - String setting ""CharacterString" (Page21) Character size "CharacterSize" (Page23)

    - Block position III "BlockPosition" (Page26) Marking parameters III "MarkingParameter" (Page27)
- · Since all commands other than the string setting Reference command have a default value, you can create new settings even if you omit these values.

#### (3) Ending the program creation You can finish editing the program using the command

described below. Command EndProgram Description Declares the end of program editing. No Target WX,EndProgram [CR] Command wx Response WX,OK [CR] Command RX No Response Parameter No

· If the settings are in their default values and the mark Reference data is the "ABC" string, the program can be configured using just three commands as described below. WX,CreateProgram=0001 [CR] WX,PRG=0001,BLK=001,CharacterString=ABC [CR]

WX,EndProgram [CR]

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- Communication Interface User's Manual -

# Communication 5. Errors

#### 5-1 **Error response**

An error response is returned if there is an error in the command format or data range. All error responses will have the error number "S\*\*\*" and error code on the end of the command.

	Send WX,Command [CR]	
	Receive	Normal response: WX,OK [CR] Error response: WX,NG,S***,ErrCode [CR]

・The "E\* " type error may occur if you send Reference "StartMarking" to start marking or "ProgramNo" to change the currently running program No. The "E\*\*\*" error is not a communication error but is occurring on the controller side. Therefore, check the error details in the User's Manual of the laser marker.

#### 5-2 **Error list**

There are following types of communication errors.		
Error No.	Error name	Remedy
S000	Program incorrect error	Check whether the parameter is within the input range. Create the program again if no corrupt location can be found.
S001	Program memory full error	Remove the unwanted programs in the controller.
S002	Built-in memory card full error	Remove the unwanted logos, fonts, and Z-MAP data in the controller.
S003	USB flash drive full error	Remove any unwanted data from the USB flash drive.
S004	USB flash drive not inserted error	Perform the operation after inserting a USB flash drive.
S005	USB flash drive cannot be recognized error	Format the USB flash drive in FAT** format and try again. Try using a different USB flash drive if the error reoccurs.
S006	Priority error	The console and/or external communication has acquired communication priority. Check if the other devices are in test marking or finder mode, and perform the operation after exiting from these modes.
S008	No-File Error	Perform the communication again using an existing file as the target.
S009	Busy Error	Perform the operation while READY is in ON state.
S010	No marking block error	Set the marking flag to ON for one or more target blocks (palettes).
S011	Logos/custom characters over error	Reduce the number of files.
S012	Illegal optimization error	Reduce the line speed or adjust the character size, etc.
S013	Scan Optimize unexecutable error	Set the quality level of all blocks to [Customize].
S014	Program operation during execution error	A currently running program cannot be deleted.
S015	Logo/custom character file operation error	First remove the program that is using the logo or custom character you wish to delete.
S016	Test Mark Unexecutable Error	Start test marking after the device has gone into READY state.
S017	Fixed point marking parameter error	Modify the program to make sure that the fixed point and 3D shape blocks are not mixed.
S018	Barcode/2D code illegal setting error	Please enter an encoding string.
S019	All-setup restoration error	Make sure to use the backup data from the same model.

Error No.	Error name	Remedy
S020	Data Length Error	Noise may be entering the external communication cable if the error occurs in a sporadic manner.
S021	Program No. unregistration error	Transfer the program to the controller by following the procedure below. Select [LASER MARKER] - [File Operations] in the ribbon menu, and then transfer the program
S022	Block# no registration error	settings to the controller. Transfer the program to the controller by following the procedure below. Select [LASER MARKER] - [File Operations] in the ribbon menu, and then transfer the program settings to the controller.
S023	Status error	Reset the error and try marking again.
S024	Illegal Command Error	Acquire the communication history and check the parameter input range and block type.
S025	Checksum Error	Check if the checksum settings for the laser marker and external devices (PLC, etc.) are both ON. If there is no problem in the above, check if the checksum calculation method of the PLC is set to horizontal parity (Exclusive OR). Noise may be entering the external communication cable if the error occurs in a sporadic manner.
S026	Format error	Acquire the communication history and check the command details. If a comma (,) is used in the string, change it to "%044A" (special code representing a comma) before sending it.
S027	Command Unrecognizable Error	Acquire the communication history and check the command details.
S028	Response data length error	Modify the request command to reduce the response data length.
S029	Mark data request error	Send the command after the marking has completed.
S030	Group number unregistered error	Group the blocks in the program using MarkingBuilder 3. You can group blocks by following the procedure below. Select and right-click on a block to open the context menu, and then select [Grouping].
S050	Quick change of character setup error	<ul> <li>Check the following when using the high speed character edit command.</li> <li>Check if the block you wish to change is subject to high speed string editing.</li> <li>Check that the string to be sent is registered as the character type that supports high speed string editing.</li> </ul>
S051	Sample Marking Unexecutable Error	Commence sample marking in READY state.
S052	Laser inspection unexecutable error	Commence inspection laser in READY state.
S060	Block type incorrect setting error	Create the program again.
S061	Block assignment incorrect setting error	Create the program again.
S062	Character size incorrect setting error	Modify the blocks whose character aspect ratio is greater than 1:5 or 5:1.
S063	Character assignment incorrect setting error	Create the program again.

Error No.	Error name	Remedy
S064	Character advanced incorrect setting error	Create the program again.
S065	Marking condition	Create the program again.
3005	incorrect setting error	Create the program again.
S066	Barcode/2D code illegal setting error	Create the program again.
S067	Continuous marking incorrect setting error	Create the program again.
S068	Movement/marking direction incorrect setting error	Create the program again.
S069	Program incorrect setting error	Create the program again.
S070	Matrix information incorrect setting error	Create the program again.
S071	Matrix cell information incorrect setting error	Create the program again.
S072	Character string incorrect setting error	Create the program again.
S073	Individual counter incorrect setting error	Create the program again.
S074	Common counter incorrect setting error	Configure the common counter settings again by following the procedure below. You can configure it by selecting [LASER MARKER] - [Marking Common] in the ribbon menu, followed by [Common Counter].
S075	Encoding information incorrect setting error	Configure the encoding setting again. You can configure it by selecting [LASER MARKER] - [Marking Common] in the ribbon menu, followed by [Encoding].
S076	System information incorrect setting error	Create the program again.
S077	Font replacement information incorrect setting error	Create the program again.
S078	Font scaling information incorrect setting error	Configure the character scaling settings again. You can configure it by selecting [LASER MARKER] - [Marking Common] in the ribbon menu, followed by [Character scaling].
S079	Font skip cross width information incorrect setting error	Configure the character skip cross settings again. You can configure it by selecting [LASER MARKER] - [Marking Common] in the ribbon menu, followed by [Character skip cross].
S080	Logo/custom character buffer information incorrect setting error	Create the program again.
S081	Current value incorrect setting error	Create the program again.
S082	3D system information incorrect setting error	Create the program again.
S083	3D information incorrect setting error	Create the program again.
S084	Operation limitation error	Delete the program that is using the [2D code reader function], or activate the [2D code reader function].

Error No.	Error name	Remedy
S085	Version of data outside support	The loaded program has been created in a higher version than the currently running MarkingBuilder 3. Upgrade the currently running Marking Builder 3 to the latest version, or downgrade the version
		of the loaded program.
S086	Wobble Incorrect Setting Error	Check if the marking line width, overlap rate and scan speed settings are within range.
S087	2D code reading error	Modify the program so that it is readable in test marking, and then run the program again.
S088	Working distance measurement error	<ul> <li>Height measurement may be impossible in the following cases:</li> <li>Distance measuring light cannot be detected correctly because of the surface condition of the workpiece.</li> <li>Distance measuring light cannot be detected because the lighting in the rack is too bright.</li> </ul>
S089	Working distance measurement limitation error	Measure the work distance in READY state.
S090	Registered barcode error	Change the barcode verification string.
S091	Barcode/2D code link setting error	<ul> <li>Please check the following:</li> <li>Check if the 2D code overprinting setting is enabled for the target block.</li> <li>Check if the target overprinting No. exists.</li> </ul>
S092	Barcode illegal registration state error	Configure it in either MarkingBuilder 3 or the console.
S093	Marking Confirmation Function Error	Check if the mark data exist in the field of view of the confirmation coordinates.
S094	TrueType font file size error	Reduce the number of TrueType font types being used.
S095	Model limitation error	Cannot be used.
S096	Open priority error	Restart the device.
S097	File Access Error	File may be read-only. Check the file attribute and try again.
S098	Serial No. error	Enter the correct serial No.
S099	Duplicate Serial No.	The serial code of the desiccant can only be used once. Purchase and replace with a new desiccant.

# Appendix

	Appendix-1							ASCII code list									
	Upper 4 bits																
		0	1	2	3	4	5	6	7	8	9	А	В	С	D	Е	F
	0	NUL	DLE	SP	0	@	Ρ	•	р				ļ	Þ	111		
	1	SOH	DC1	!	1	А	Q	а	q			0	7	チ	Д		
	2	STX	DC2	=	2	В	R	b	r			5	$\prec$	ッ	メ		
	3	ETX	DC3	#	3	С	S	с	s			J	ウ	デ	モ		
	4	EOT	DC4	\$	4	D	Т	d	t			`	Н		ヤ		
_	5	ENQ	NAC	%	5	Е	U	е	u			·	¥	ナ	ц		
Lower 4	6	ACK	SYN	&	6	F	V	f	v			ヲ	力	Ц	Π		
	7	BEL	ETB	•	7	G	w	g	w			7	#	R	ラ		
bits	8	BS	CAN	(	8	Н	Х	h	х			イ	ク	ネ	IJ		
	9	ΗT	EM	)	9	I	Y	i	у			ウ	ケ	ノ	ル		
	А	LF	SUB	*		J	Ζ	j	z			Н	П	ト	ン		
	В	VT	ESC	+	• ,	к	[	k	{			女	サ	Ł	Ц		
	С	FF	FS	,	<	L	¥	Ι	_			ヤ	~	フ	ワ		
	D	CR	GS	-	=	М	]	m	}			ユ	ス	<	$\sim$		

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# Appendix-2 Model-Specific Input Value List

		MD-X1000/1500 series			MD-F3200	/5200 series	MD-U10	00 series	ML-Z9600 series		
Parameter	Unit	Standard area Wide area		Small Standard spot area		Wide area	Standard	andard area Wide area		Wide area	Small spot
		MD-X1000 /1500	MD-X1020 /1520	MD-X1050	MD-F3200 /5200	MD-F3220 /5220	MD-U1000	MD-U1020	area ML-Z9610	ML-Z9620	ML-Z9650
Line width	mm	0.010 to	0.010 to	0.010 to	0.010 to	0.010 to	0.010 to	0.010 to	0.010 to	0.010 to	0.010 to
		5.000	7.500	2.500	5.000	7.500	5.000	7.500	5.000	7.500	2.500
Height/Width	mm	000.100 to 125.000	000.100 to 330.000	000.001 to 050.000	000.100 to 125.000	000.100 to 300.000	000.010 to 125.000	000.010 to 330.000	000.100 to 125.000	000.100 to 300.000	000.100 to 050.000
Logo	mm	000.002 to	000.005 to	000.001 to	000.002 to	000.002 to	000.002 to	000.005 to	000.002 to	000.005 to	000.001 to
Height/Width Arc character		125.000 000.000 to	330.000 000.000 to	50.000 000.000 to	125.000 000.000 to	300.000 000.000 to	125.000 000.000 to	330.000 000.000 to	120.000 000.000 to	300.000 000.000 to	050.000 000.000 to
space	mm	180.000	450.000	075.000	180.000	450.000	180.000	450.000	180.000	450.000	075.000
Character space	mm	000.000 to	000.000 to	000.000 to	000.000 to	000.000 to	000.000 to	000.000 to	000.000 to	000.000 to	000.000 to
Character full		180.000 000.100 to	450.000 000.100 to	075.000 000.100 to	180.000 000.100 to	450.000 000.100 to	180.000 000.010 to	450.000 000.010 to	180.000 000.100 to	450.000 000.100 to	075.000 00.100 to
width/full height	mm	180.000	450.000	075.000	180.000	450.000	180.000	450.000	180.000	450.000	075.000
Character pitch	mm	-180.000 to 0180.000	-450.000 to 0450.000	-075.000 to 0075.000	-180.000 to 0180.000	-075.000 to 0075.000	-180.000 to 0180.000	-450.000 to 0450.000	-180.000 to 0180.000	-450.000 to 0450.000	-075.000 to 0075.000
Barcode height	mm	000.200 to	000.300 to	000.100 to	000.200 to	000.300 to	000.200 to	000.300 to	000.200 to	000.300 to	000.100 to
Linear code		125.000 000.200 to	330.000	050.000	125.000	300.000	125.000	330.000 000.500 to	120.000	300.000 000.500 to	050.000
height	mm	125.000	000.500 to 330.000	000.100 to 050.000	000.200 to 125.000	000.500 to 300.000	000.200 to 125.000	330.000	000.200 to 120.000	300.000	000.100 to 050.000
X coordinate	mm	-062.500 to	-165.000 to	-025.000 to	-062.500 to	-150.000 to	-062.500 to	-165.000 to	-060.000 to	-150.000 to	-025.000 to
		0062.500 -062.500 to	0165.000 -165.000 to	0025.000 -025.000 to	0062.500 -062.500 to	0150.000 -150.000 to	0062.500 -062.500 to	0165.000 -165.000 to	0060.000 -060.000 to	0150.000 -150.000 to	0025.000 -025.000 to
Y coordinate	mm	0062.500	0165.000	0025.000	0062.500	0150.000	0062.500	0165.000	0060.000	0150.000	0025.000
Z coordinate	mm	-021.000 to	-021.000 to	-015.000 to	-021.000 to	-021.000 to	-021.000 to	-021.000 to	-021.000 to	-021.000 to	-002.000 to
Sphere diameter,		0021.000	0021.000	0015.000	0021.000	0021.000	0021.000	0021.000	0021.000	0021.000	0002.000
Cylinder diameter Bottom diameter of cone,	mm	0000.200 to 0480.000	0000.200 to 1200.000	0000.200 to 0200.000	0000.200 to 0480.000	0000.200 to 1200.000	0000.200 to 0480.000	0000.200 to 1200.000	0000.200 to 0480.000	0000.200 to 1200.000	0000.200 to 0200.000
Top diameter of cone		0480.000	1200.000	0200.000	0480.000	1200.000	0480.000	1200.000	0480.000	1200.000	0200.000
Cone height	mm	000.100 to 125.000	000.100 to 330.000	000.100 to 050.000	000.100 to 125.000	000.100 to 300.000	000.100 to 125.000	000.100 to 330.000	000.100 to 120.000	000.100 to 300.000	000.100 to 050.000
Scan speed	mm/s	00001 to 12000	00001 to 08000	00001 to 06000	00001 to 12000	00001 to 08000	00001 to 12000	00001 to 08000	00001 to 12000	00001 to 06000	00001 to 06000
Approach scan speed	mm/s	0 to 04000	0 to 06000	0 to 02000	0 to 04000	0 to 06000	0 to 04000	0 to 06000	0 to 06000	0 to 09999	0 to 03000
Pulse frequency	kHz		000 to 400		060 1	to 120	000, 04	0 to 400		-	
Spot variable	-	-210 to 0210	-210 to 0210	-150 to 0150	-210 to	-210 to 0210	-210 to 0210	-210 to 0210	-210 to 0210	-210 to 0210	-020 to 0020
•		00.000 to	00.000 to	00.000 to	0210				00.000 to	00.000 to	00.000 to
Deep dig amount	mm	42.000	42.000	30.000		to 42.000		o 42.000	42.000	42.000	42.000
Matrix Height/Width	mm	000.000 to 125.000	000.000 to 330.000	000.000 to 050.000	000.000 to 125.000	000.000 to 300.000	000.000 to 125.000	000.000 to 330.000	000.000 to 120.000	000.000 to 300.000	000.000 to 050.000
Line speed	mm/s	0000.1 to	0000.1 to	0000.1 to	0000.1 to	0000.1 to	0000.1 to	0000.1 to	0000.1 to	0000.1 to	0000.1 to
Line speed	11111/3	4000.0	2000.0	2000.0	4000.0	2000.0	4000.0	2000.0	4000.0	2000.0	2000.0
Start Position	mm	-062.500 to 0062.500	-165.000 to 0165.000	-025.000 to 0025.000	-062.500 to 0062.500	-150.000 to 0150.000	-062.500 to 0062.500	-165.000 to 0165.000	-060.000 to 0060.000	-150.000 to 0150.000	-025.000 to 0025.000
End Position	mm	-062.500 to	-165.000 to	-025.000 to	-062.500 to	-150.000 to	-062.500 to	-165.000 to	-060.000 to	-150.000 to	-025.000 to
Z coordinate		0062.500	0165.000	0025.000	0062.500	0150.000	0062.500	0165.000	0060.000	0150.000	0025.000
correction amount	mm	-42.000 to 042.000	-42.000 to 042.000	-30.000 to 030.000	-42.000 to 042.000	-42.000 to 042.000	-42.000 to 042.000	-42.000 to 042.000	-42.000 to 042.000	-42.000 to 042.000	-04.000 to 004.000
Upper tolerance limit	mm	-20.999 to 042.000	-20.999 to 042.000	-14.999 to 030.000	-20.999 to 042.000	-20.999 to 042.000	-20.999 to 042.000	-20.999 to 042.000	-20.999 to 042.000	-20.999 to 042.000	-01.999 to 004.000
Lower tolerance	<b>m</b> m	-42.000 to	-42.000 to	-30.000 to	-42.000 to	-42.000 to	-42.000 to	-42.000 to	-42.000 to	-42.000 to	-04.000 to
limit Movement	mm	020.999	020.999	014.999	020.999	020.999	020.999	020.999	020.999	020.999	001.999
reference point											
X/Y coordinates (Correct inside	mm	-062.500 to 0062.500	-165.000 to 0165.000	-025.000 to	-060.000 to 0060.000	-150.000 to 0150.000	-062.500 to	-165.000 to	-060.000 to 0060.000	-150.000 to 0150.000	-025.000 to
the horizontal		0062.500	0165.000	0025.000	0060.000	0150.000	0062.500	0165.000	0060.000	0150.000	0025.000
plane) Correction					<u> </u>				<u> </u>		
amount X/Y (Correct inside	mm	-125.000 to	-330.000 to	-050.000 to	-125.000 to	-300.000 to	-125.000 to	-330.000 to	-120.000 to	-300.000 to	-050.000 to
the horizontal	mm	0125.000	0330.000	0050.00	0125.000	0300.000	0125.000	0330.000	0120.000	0300.000	0050.00
plane) X/Y coordinates											
position correction	mm	-062.500 to 0062.500	-165.000 to 0165.000	-025.000 to 0025.000	-062.500 to 0062.500	-150.000 to 0150.000	-062.500 to 0062.500	-165.000 to 0165.000	-060.000 to 0060.000	-150.000 to 0150.000	-025.000 to 0025.000
in the unit setup		0002.000	0103.000	0023.000	0002.300	0150.000	0002.000	0103.000	0000.000	0150.000	0023.000
Z coordinate position correction in the unit setup	mm	-21.000 to 021.000	-21.000 to 021.000	-15.000 to 015.000	-21.000 to 021.000	-21.000 to 021.000	-21.000 to 021.000	-21.000 to 021.000	-21.000 to 021.000	-21.000 to 021.000	-02.000 to 002.000

# **Revision History**

Date of printing	Version	Revision contents					
April 2015	Official release						
September 2015	2nd edition	MARKING BUILDER 3 Ver					
		2.2 supported					
September 2015	3rd edition	Variable Revisions					
March 2016	4th edition	Correction					
December 2016	5th edition	Added the MD-F3200/5200					
		series					
January 2018	Revised 1st	Added the MD-U1000 and					
	edition	ML-Z9600 series					
June 2018	2nd revision	Add the counter reset					
	1st edition	timing.					

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